

### **Our team**



Francisco Soriano

CPE - VLSI Track



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CPE - Comprehensive Track



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CPE - Comprehensive Track



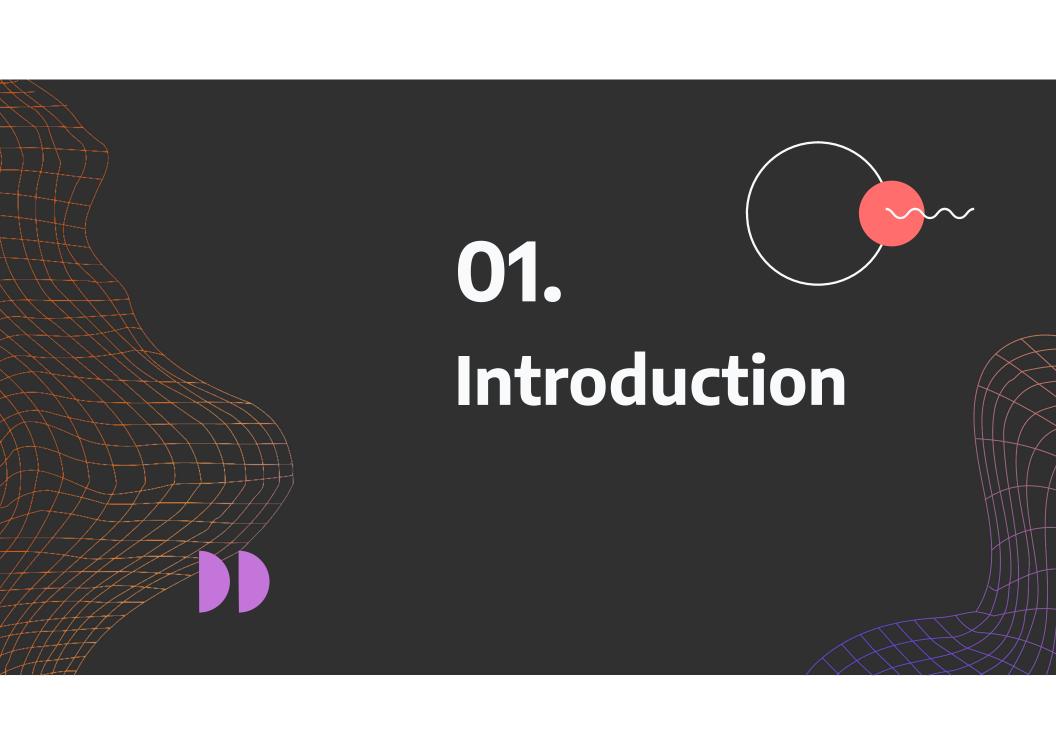
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### **Motivations**

#### **Passion**

Immersive Storytelling

How can we combine this with Projection Mapping?

#### **Inspiration**

Disney projection mapping advancements

How can we bring these capabilities to normal people?

#### **Proposal**

GPMS: A portable system using generative AI for themed projections on any surface/structure

#### **Opportunity**

Pitch GPMS to local entertainment venues in Orlando, FL

• What does a use case look like?



To make projection mapping using generative Al accessible to everyday consumers



### What is GPMS?

A device enabling a simple *GUI* to calibrate and generate unique images for structures

Device consists of:

- Raspberry Pi
- Touch Screen Display
- Projector
- Camera

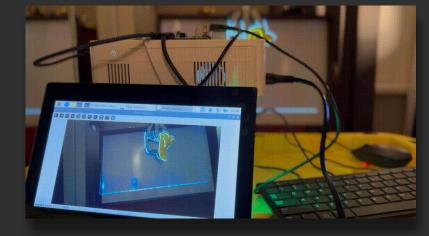


Connected via **API** to a server running a **generative AI** stack

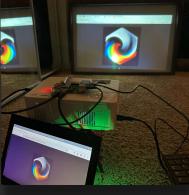














### **Basic Goals & Objectives**



#### **Projection**

Project images onto structures using computer vision

#### Structure Alignment

Generated image aligns with features on the structure



#### **Interaction**

Touchscreen input + generative AI for image creation

# User Input Projection

Projector displays images aligned with user input



#### **Power**

Configure sufficient power supply for GPMS

# Reliable Power Supply

Reliable power supply via optimal Power Bank

### **Advanced Goals & Objectives**

#### **Increased Control**

Empower users with greater control over the generated images based on input and preferences.



#### **Image Outlines**

Implement slider inputs for users to set edge detection thresholds, fine-tuning the outlines used to generate images.



#### **Image Styles**

Add options for users to specify image style, such as animated or realistic, to guide the generation process.



### Stretch Goals & Objectives



Emphasize specific structural elements

#### **Area Selection**

Enable users to select specific portions of the input image they want to focus on.



Automatic calibration for ease of use

# Device to Structure

Automatic device calibration to structure



Advanced Power Supply Unit (PSU)

#### **PSU PCB**

Custom PCB with buck-down regulator for voltage/current control



# **Project Specifications**

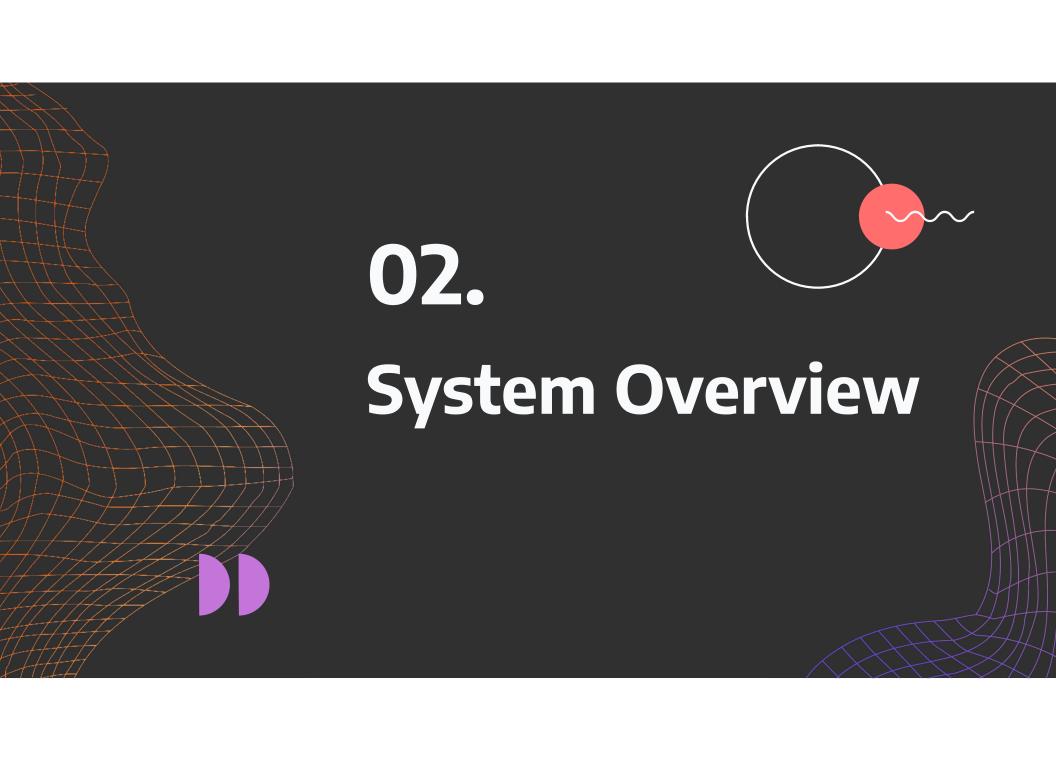
Category	Target
Size	12 in x 12 in x 5 in
Weight	~10 pounds
Battery Life	~1 hour
Recover Time	< 1 minute / image
Elapsed Time	< 2 minutes
Alignment Accuracy	> 90%
Al Generation Time	< 1.5 minute / image



# **Project Specifications**

Category	Target	
Size	12 in x 12 in x 5 in	
Weight	~10 pounds	
Battery Life	~1 hour	
Recover Time	< 10 seconds	
Elapsed Time	< 5 minutes	
Alignment Accuracy < 8 mm		
Al Generation Time	< 1.5 minute / image	





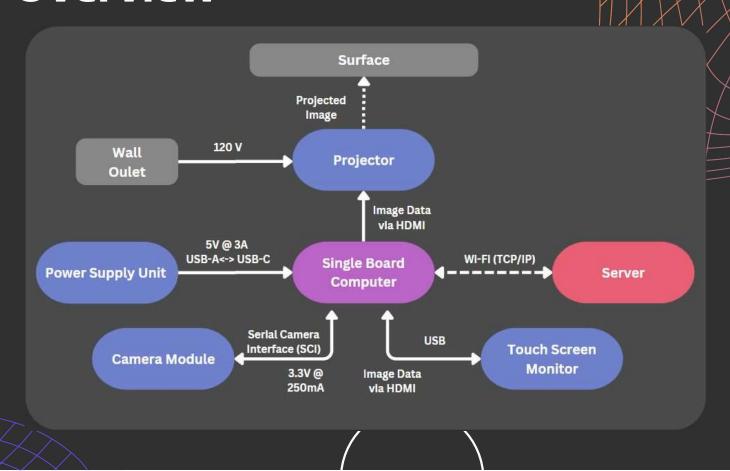
## **Visual Product Representation**







### → → Hardware Block Diagram -Overview



# Significant Decisions - Computing Options

	Single Board MCU Computer (SBC)		Development Board
Display	High Fidelity		Simple
Peripherals	X	X	X
Operating System	X		
Ease of Integration	Simple	Complex	Moderate
Price	\$60	~\$1 - \$10	\$10 - \$30



Raspberry Pi 5

## Significant Decisions - Computing Options

	Single Board Computer (SBC)	MCU	Development Board
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Price	\$60	~\$1 - \$10	\$10 - \$30



Raspberry Pi 5

Selection justification - simple to use



## Significant Decisions - PSU for SBC

	PCB with Regulator	Power Charger/ Bank
Stability	Potential for inconsistent/insufficient power supply	Stable/consistent power supply
Safety	Thermal Runaway	Built in protection
Time to Obtain	~ 2 weeks	Next Day
Ease of Integration	Complex	Simple
Cost	\$50 per iteration	\$74.99



RoyPow PD Power Station



## Significant Decisions - PSU for SBC

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Cost	\$50 per iteration	\$74.99

Selection justification - more efficient/safe



RoyPow PD Power Station





### Significant Decisions - Wireless Com.

	Bluetooth	Wi-Fi
Image Handling Throughput	Low Bandwidth	Higher Bandwidth
Client Server Model Integration	Not Optimal	Optimal
Overall Ease of Integration	No	Yes



Wi-Fi





### Significant Decisions - Wireless Com.

	Bluetooth	Wi-Fi
Image Handling Throughput	Low Bandwidth	Higher Bandwidth
Client Server Model Integration	Not Optimal	Optimal
Overall Ease of Integration	No	Yes



Wi-Fi

Selection justification - most practical integration





### Significant Decisions - Touchscreen

	Resistive Touch	Capacitive Touch	Infrared Touch
Touch Technology	Pressure sensitive	Responds to electrical conductivity	Uses infrared light
Multi-touch Support	No multi-touch support	Excellent multi-touch support	Good multi-touch support
Visibility	Reduced Clarity	Clear	Clear
Cost	Less Expensive	More Expensive	Most Expensive



GeeekPi 10.1 Inch Capacitive
Touchscreen





### Significant Decisions - Touchscreen

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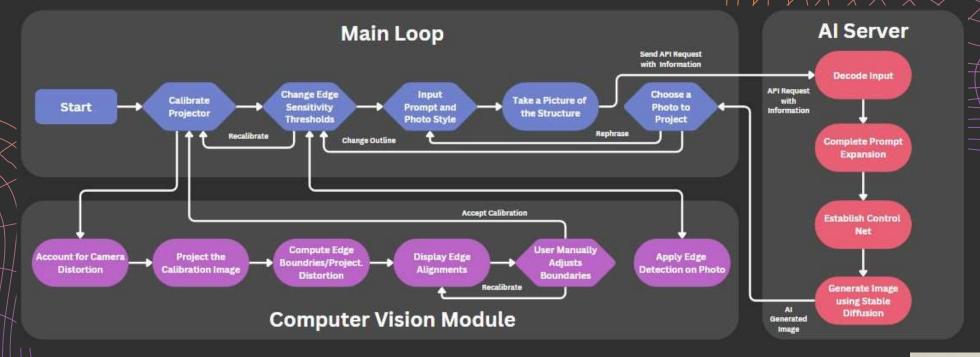
GeeekPi 10.1 Inch Capacitive
Touchscreen



Selection justification – most suitable/optimal for UI



### Software Block Diagram -**Overview**

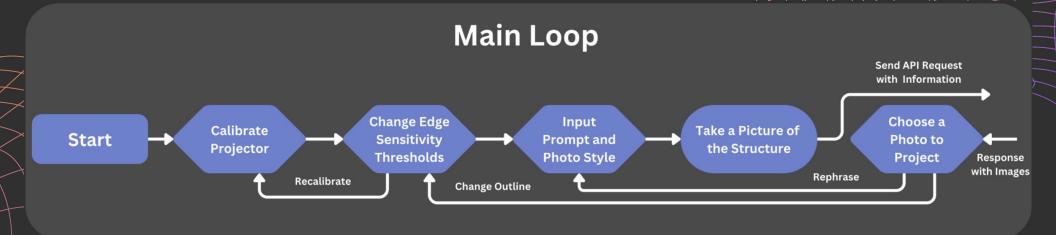








# >> Software Block Diagram -**Application**

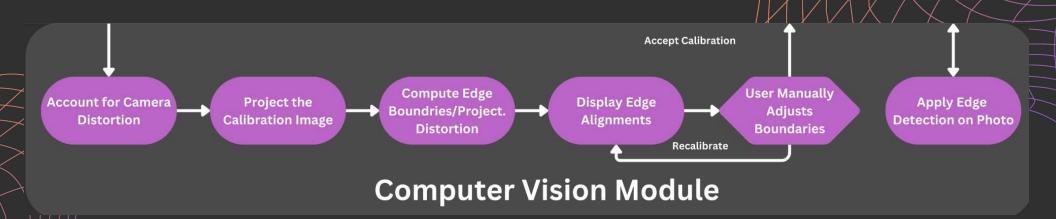








## Software Block Diagram -**Computer Vision**





# Software Block Diagram - Generative Al Server

Open a designated port on the machine to accept POST requests to the Python server

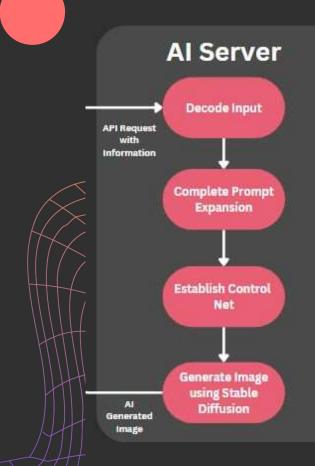
- *Input*: Incoming prompt and image capture
- Output: Outgoing selection of Al images

Utilize Stable Diffusion w/ Control Nets



+









# **Significant Decisions**

	QT	Electron	Flutter
Programming Language	C++	JavaScript (HTML/CSS)	Dart
OpenCV Integration	Easy (built-in support)	Moderate (requires additional libraries)	Moderate (requires additional libraries)
Performance	High	Good	High
Ease of Use	Moderate to complex	Easy (for web developers)	Moderate



QT



# **Significant Decisions**

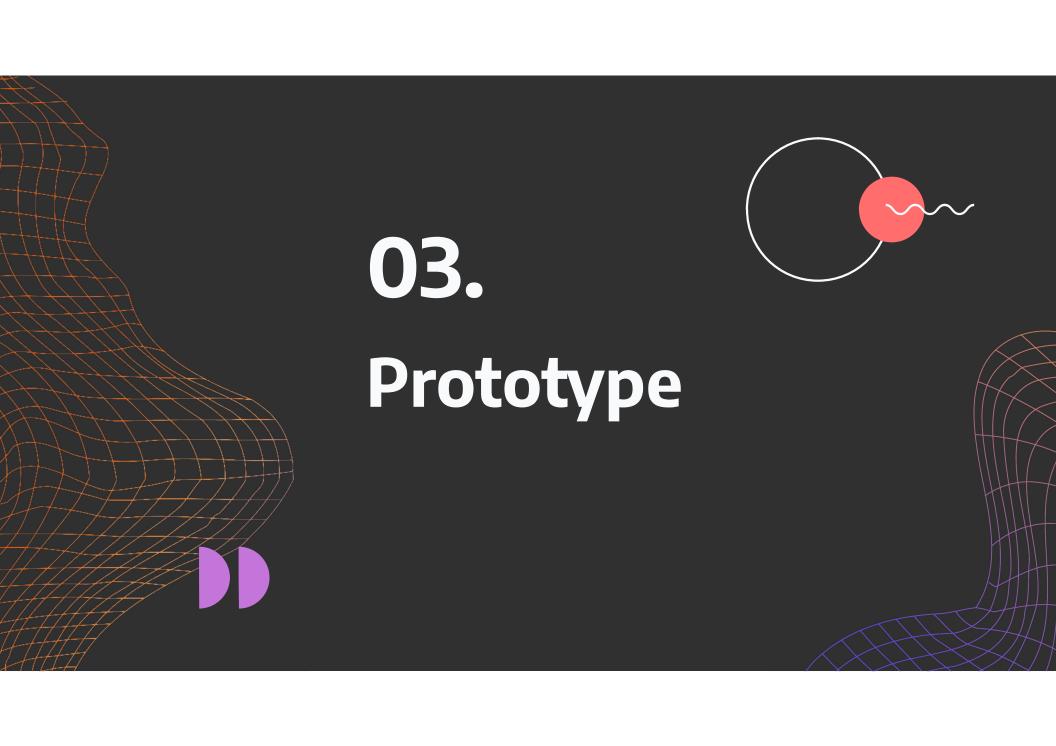
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Qt

QT

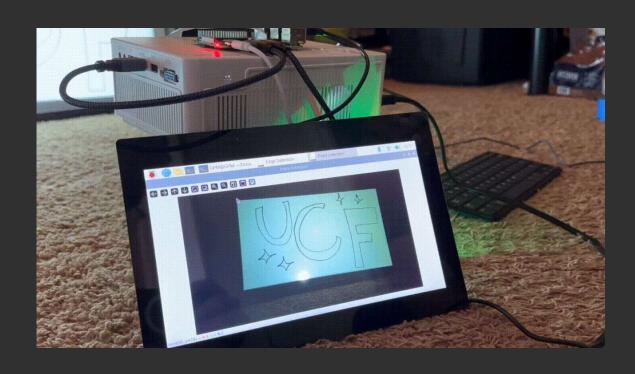






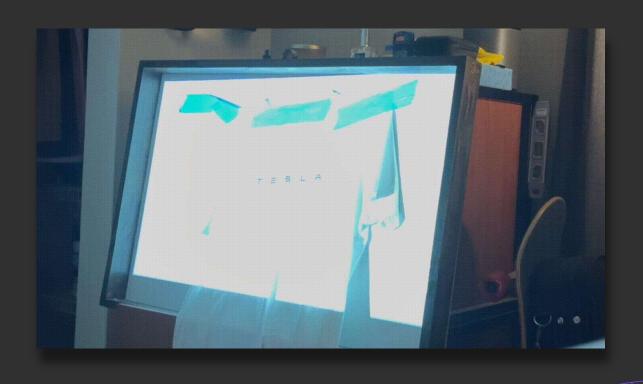


### Initial Computer Vision Implementation





### Initial Computer Vision Implementation







#### MAKE YOUR VISION COME TO LIFE

Transform your space with GPMS, an Al-powered projection mapping system to create stunning visuals based on your environment and imagination.

#### **Projection Steps**

1) Calibrate the camera

Optimize the system to accurately capture your environment.

2) Input your vision

Input your creative concept and desired outcome.

3) Choose your image

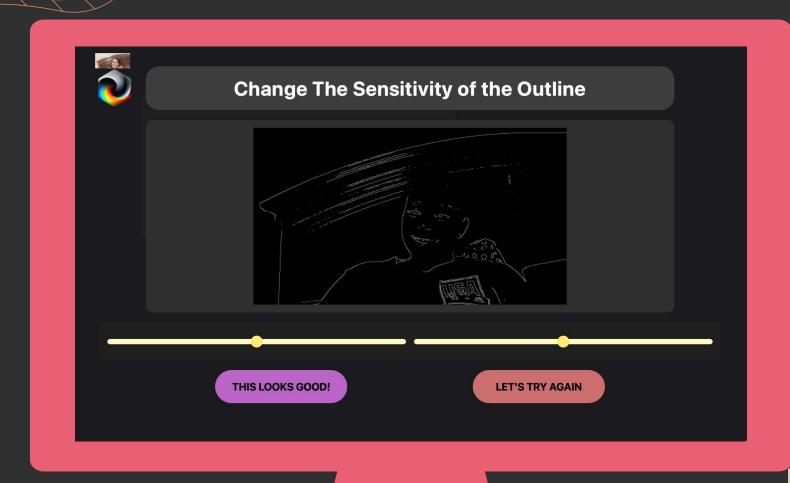
Select an image to project.

Preview of Your Projection Will Appear Here

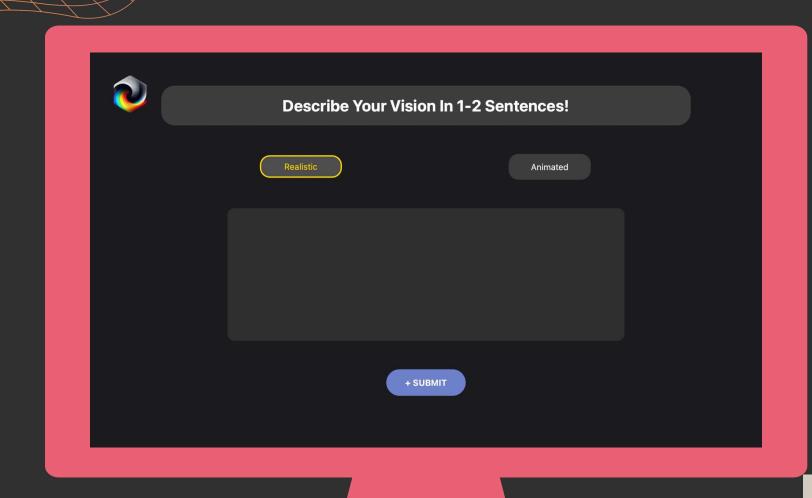
**CREATE YOUR VISION** 





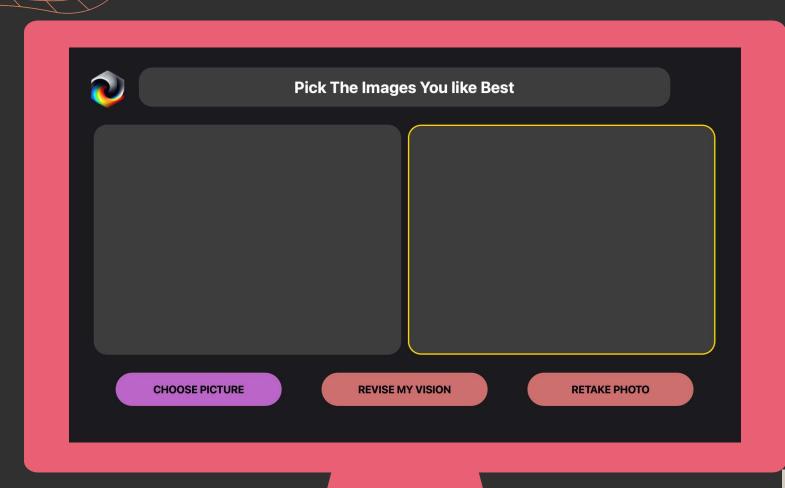










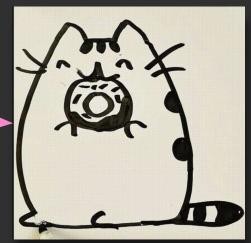






Initial Stable Diffusion Implementation





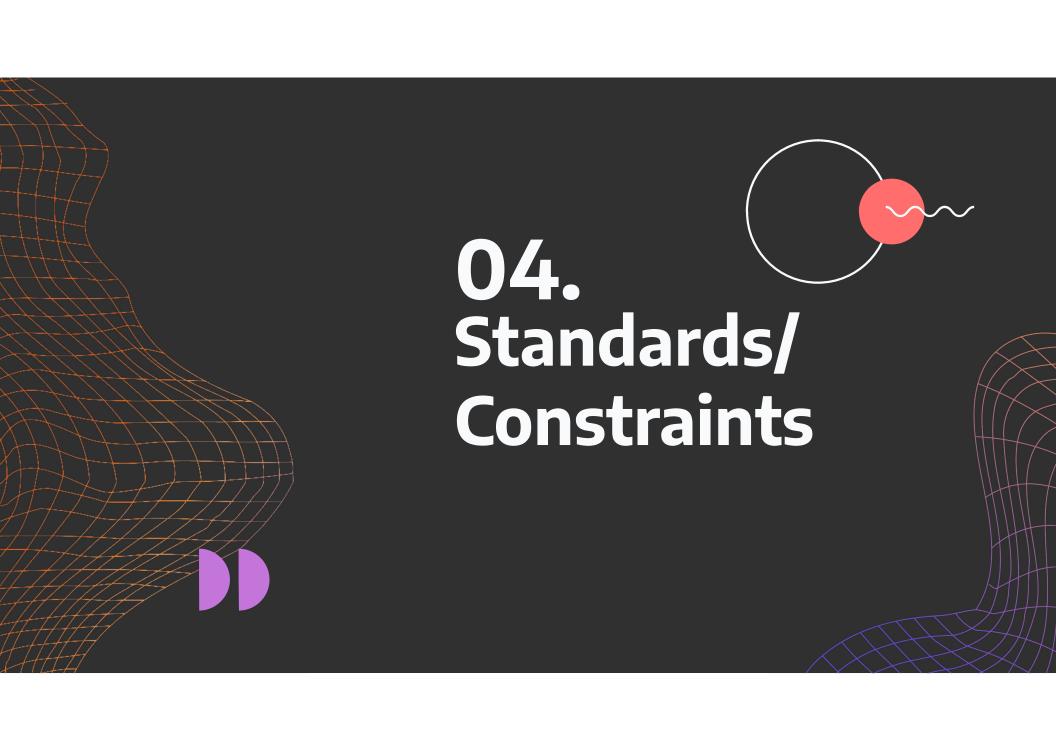
#### Stable Diffusion

 Generates images from text descriptions using a compressed diffusion process



Initial Stable Diffusion Implementation





# **Design Standards**

## **HDMI**

Provides a dependable/efficient communication channel

# **Projector**

Resolution for image details

### **TCP**

Reliable, acknowledgment drive Transport Protocol

## Camera

Resolution, noise, sensitivity, and image quality,

### **USB**

Higher power delivery, versatile



# **Design Constraints**

### **Economic**

Affordable to developers and consumers

## Security

When networking on UCF Wifi safety comes first to protect UCF and our sponsor's machine

## Time

Limited time due to administrative efforts of SD1 and integration issues

# **Network Integration**

Because the Server exists on UCF's network, you must be on campus to use GPMS

## **Ethics**

Concerns regarding copyright and inappropriate images





# **Work Distribution**

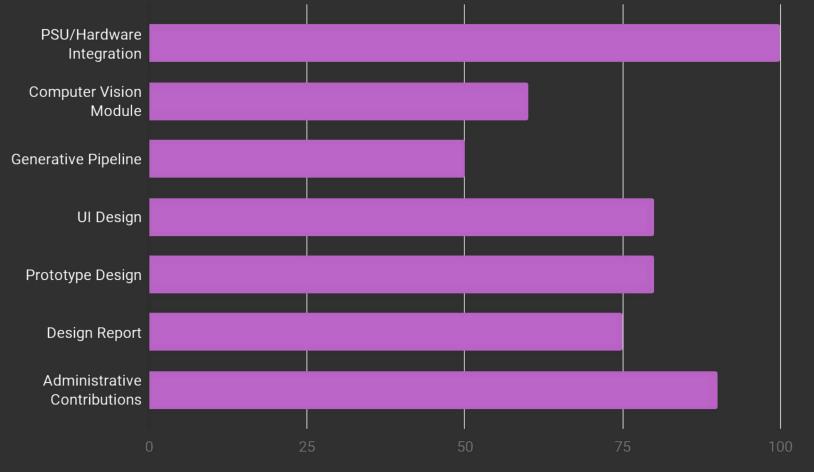
	Francisco Soriano	Declan Carter	Victoria Moreno
PSU/Hardware Integration	1st	2nd	
Computer Vision Software Stack		2nd	1st
UI Interface Design	2nd		1st
Generative Al Pipeline		1st	2nd
Administrative Contributions	1st	2nd	
Prototype Design	X	X	X

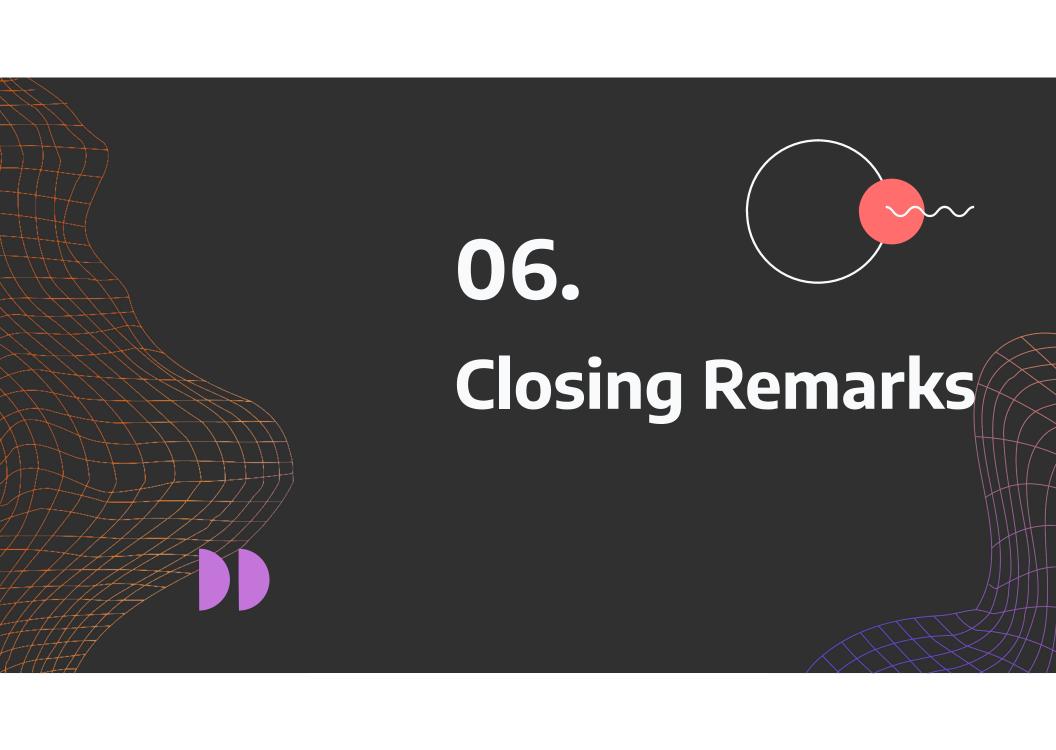


# **Bill of Materials**

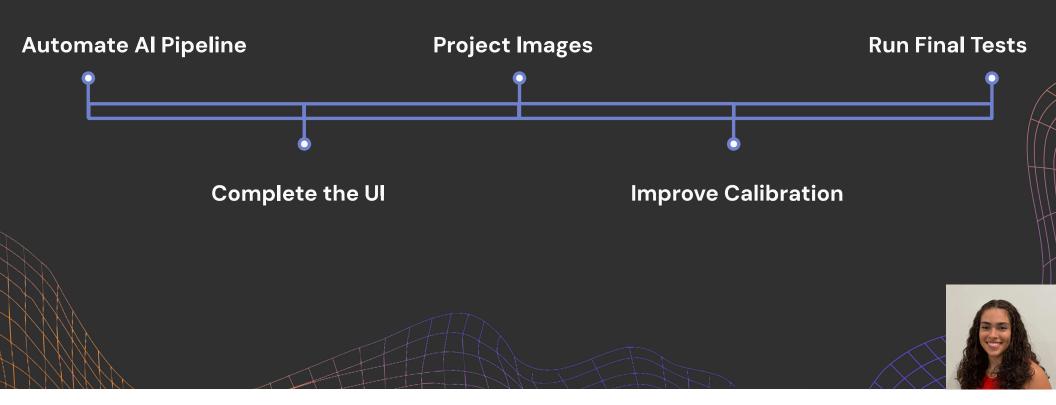
Item	Price (USD)	
Raspberry Pi 5	60.79	
Camera	5.00	
Monitor	89.99	
Projector	63.89	
AMD Machine	3244.44	
Total Pre Donation	~3,544.37	
Total Post Donation	~219.67	

# **Progress**











# Thank You!

Do you have any questions? Let's collaborate!

Our website:

https://maverick.eecs.ucf.edu/seniordesig n/sp2024su2024/g17/



