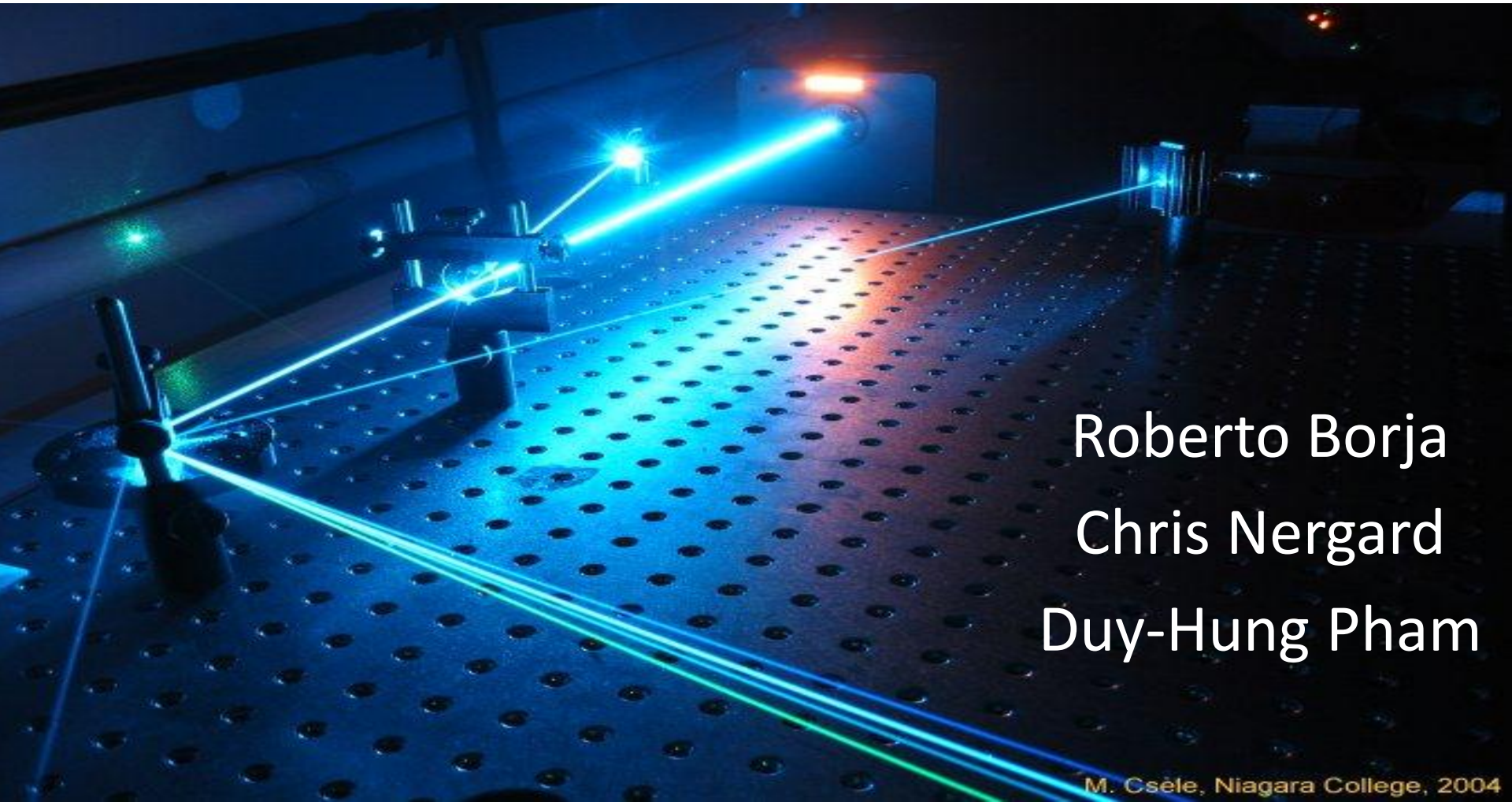


Automated Optical Setup

Group #16



Roberto Borja
Chris Nergard
Duy-Hung Pham

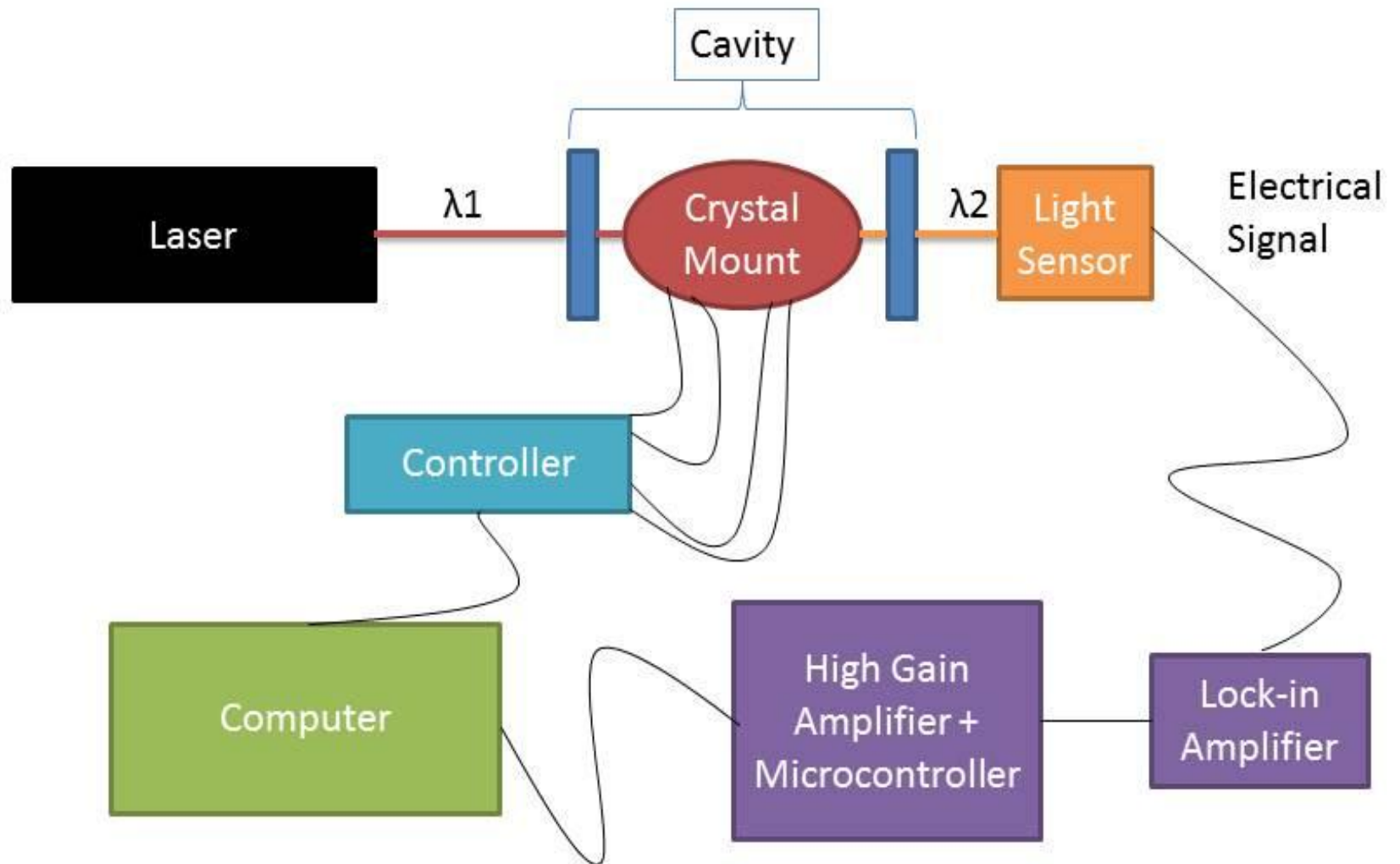
Problem

- Optical Parametric Oscillators requires a very precise orientation of a crystal
- Doing this by hand is very tedious
- Constant adjustment of crystal due to noise
- The crystal degrades the power of the laser beam significantly
- Optical experiments require very sensitive setups

The AOS Project

The project is to create an automated setup that involves rotating an optical element that a laser beam will pass through ending up at a sensor that will measure the intensity of that beam. Automation allows for a convenient, time saving, and accurate experiment.

Optical Parametric Oscillator



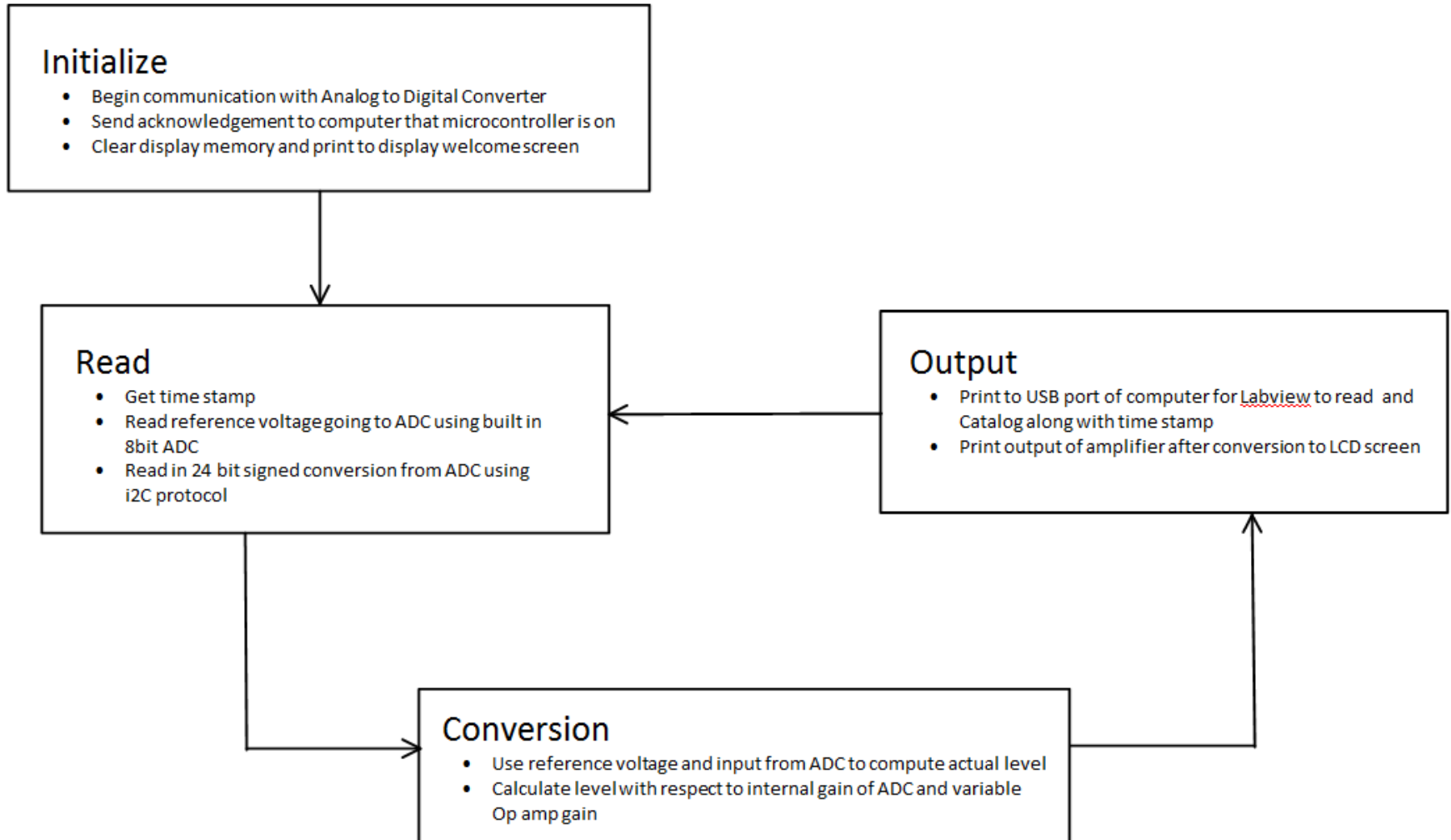
Goals

- High precision
- Absolute position of mount known
- Quick response
- No motor burnout
- Smooth adjustment
- User friendly
- Multifunction
 - Automation
 - Manual

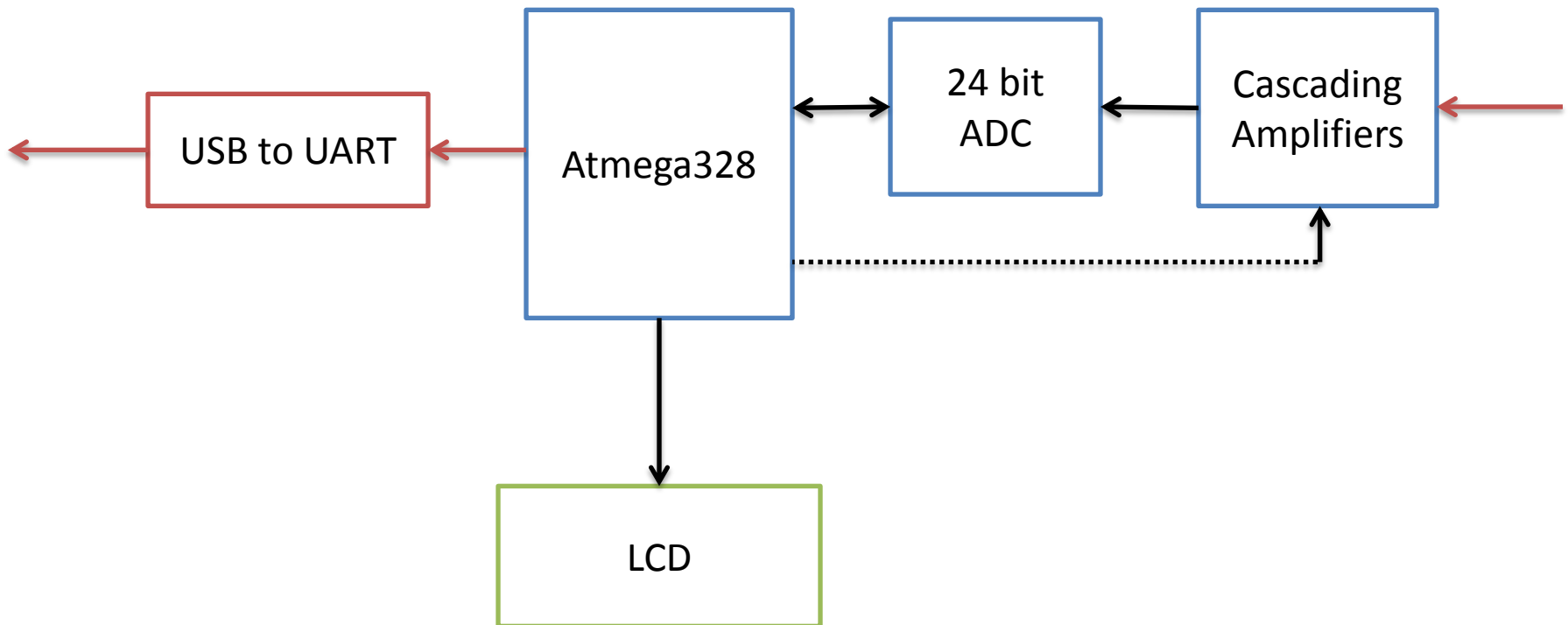
Specification

Component	Parameter	Design Specification
Amplifier	Gain	46656
Amplifier	RF signal	< 15 kHz
Mount	Position accuracy	0.1°
Mount	Adjustment sensitivity	$2 \mu rad$
Mount	Speed	$0.5^{\circ}/s$
Mount	Angular Range	$\pm 2^{\circ}$
Mount	Thickness	< 35mm
Display	Dimensions	< 25mm, 60mm
Display	Number of characters	> 10
GUI	Update time	<2s

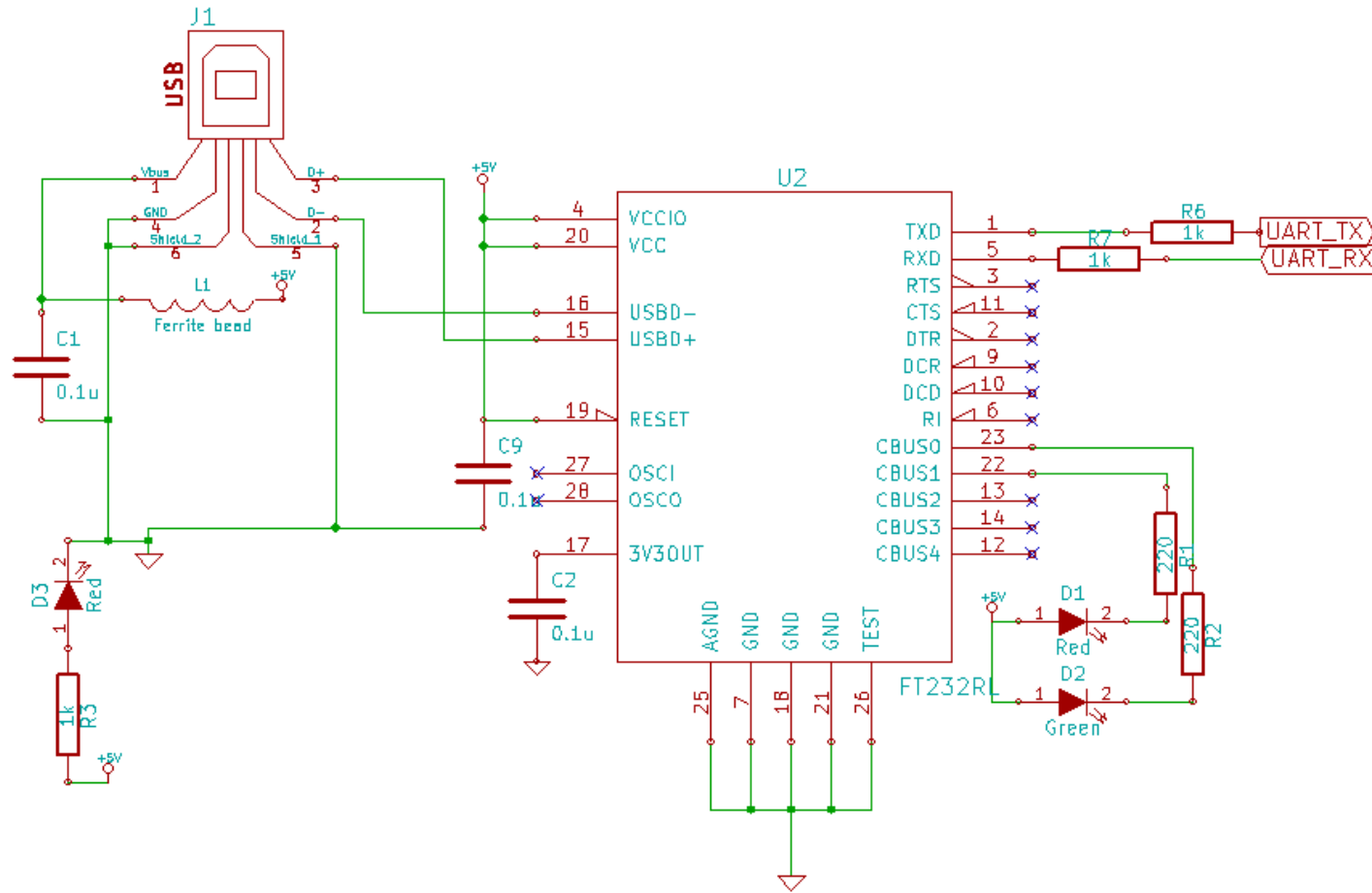
Atmega Block diagram



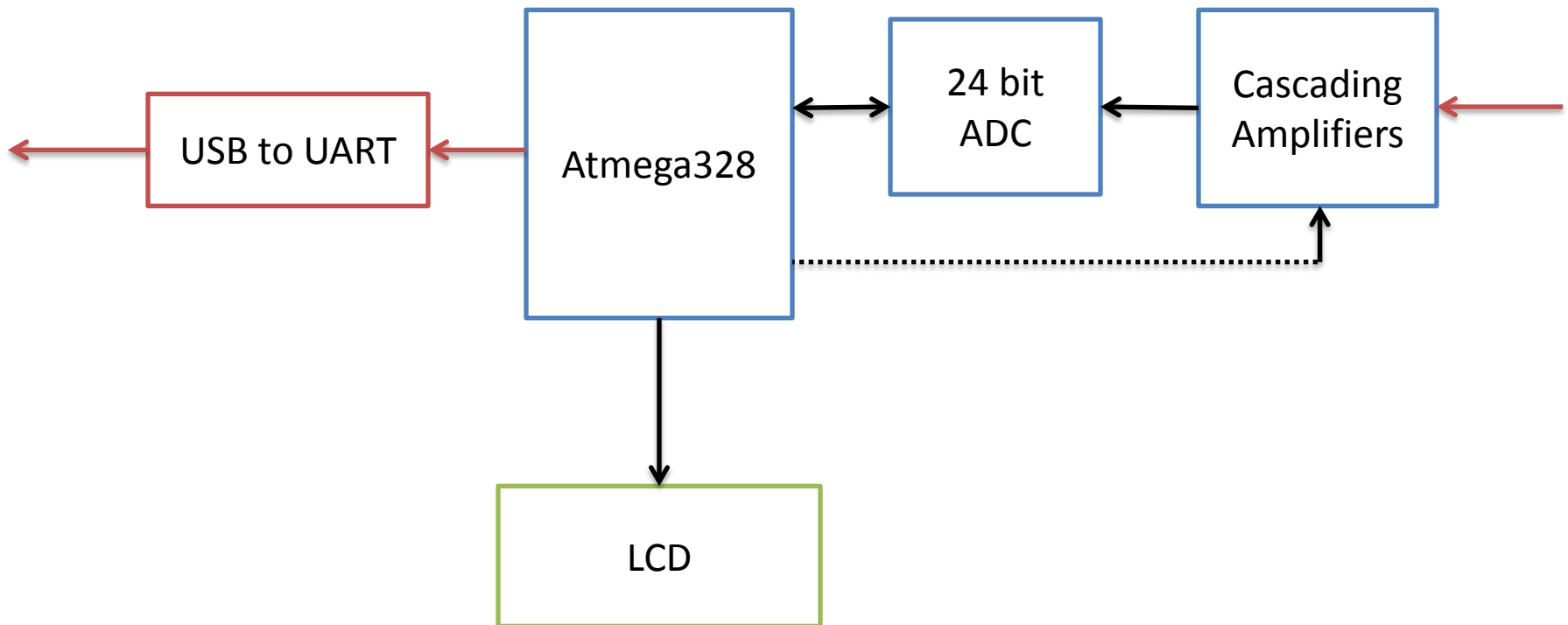
Hardware diagram



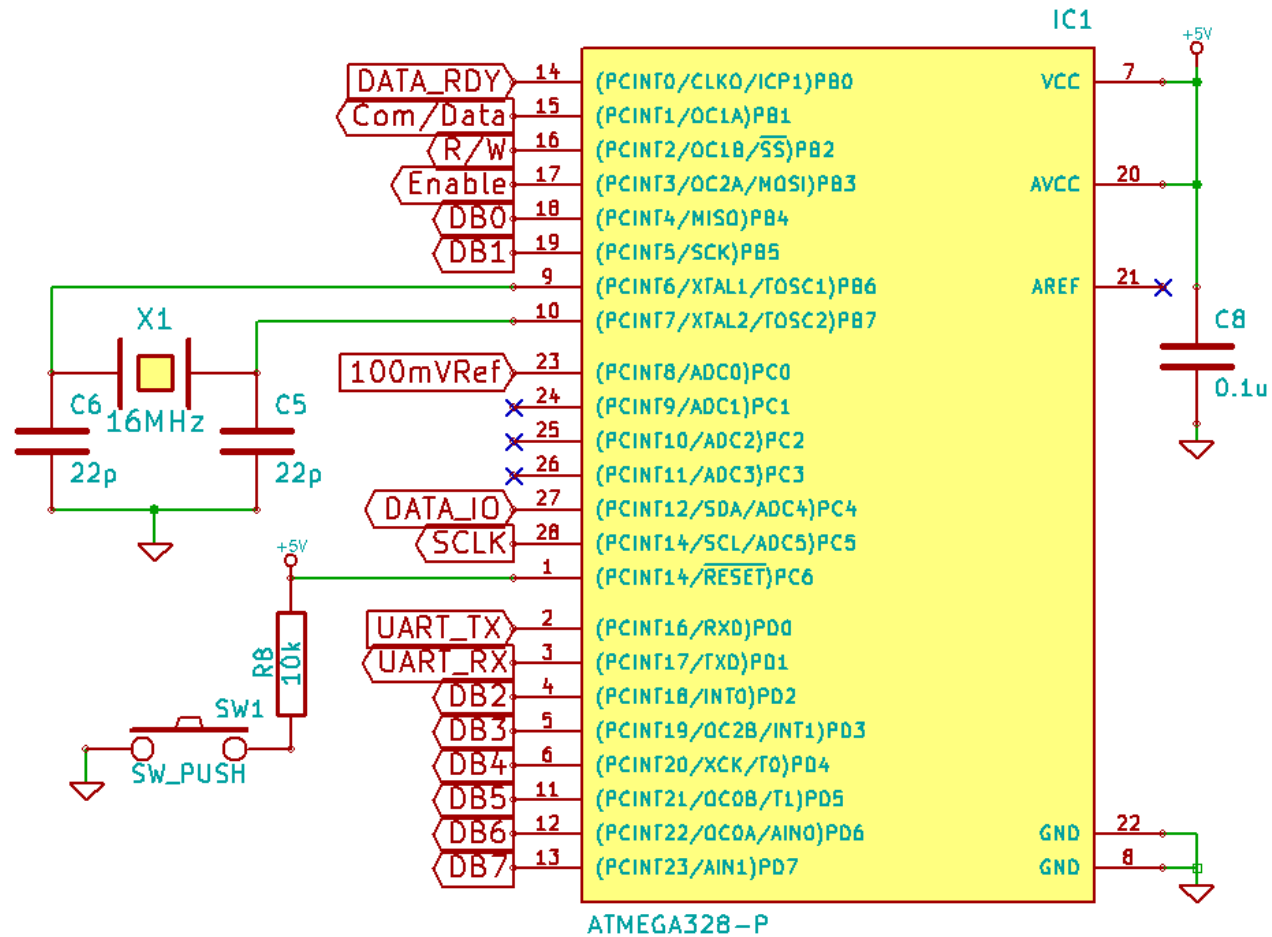
USB to UART



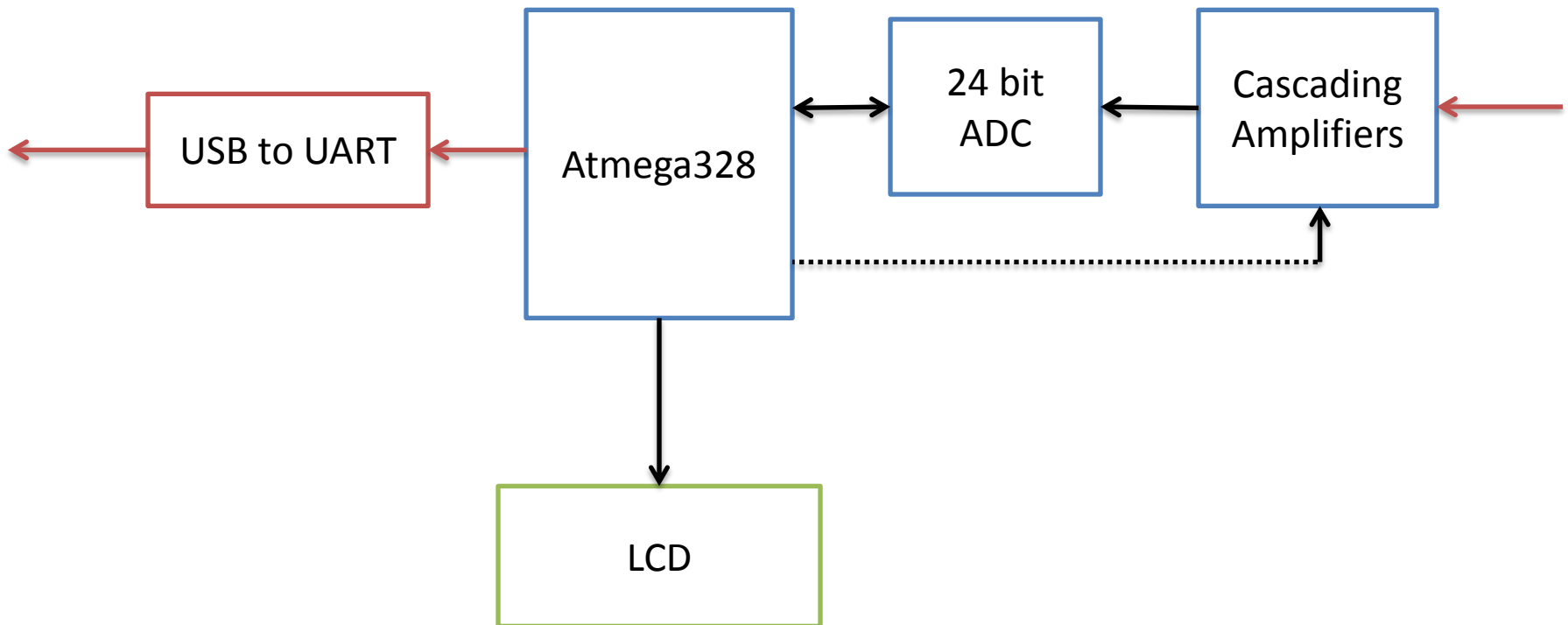
Hardware diagram



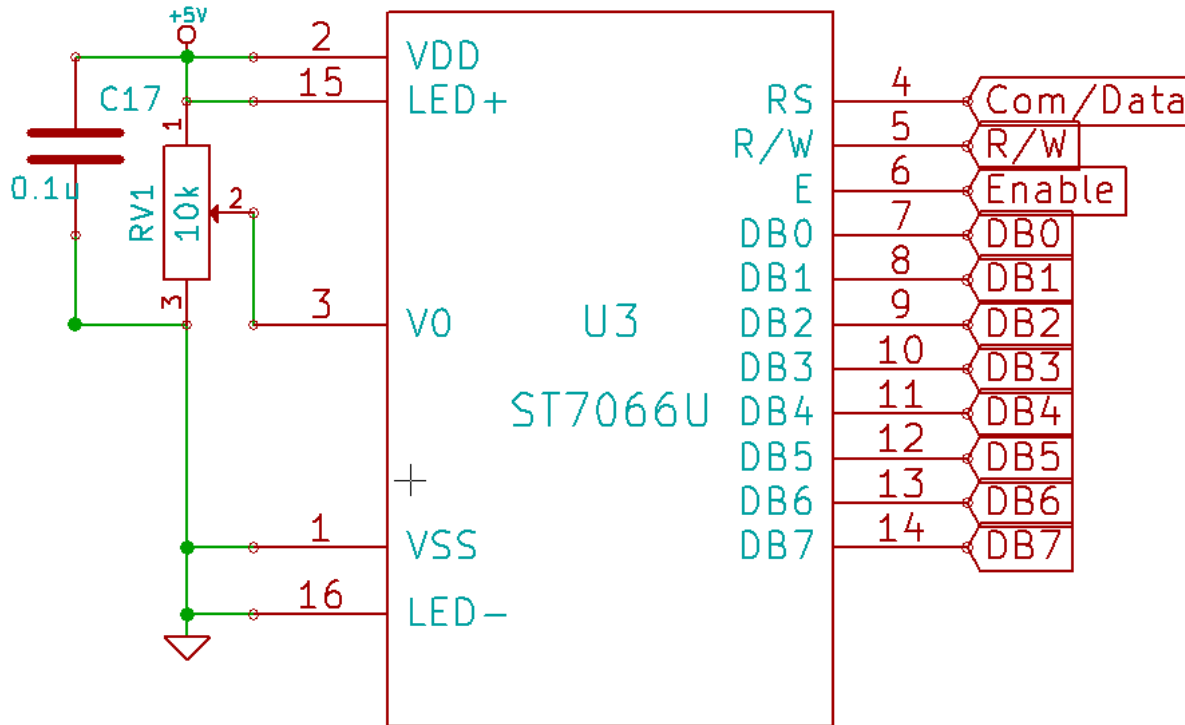
Atmega328



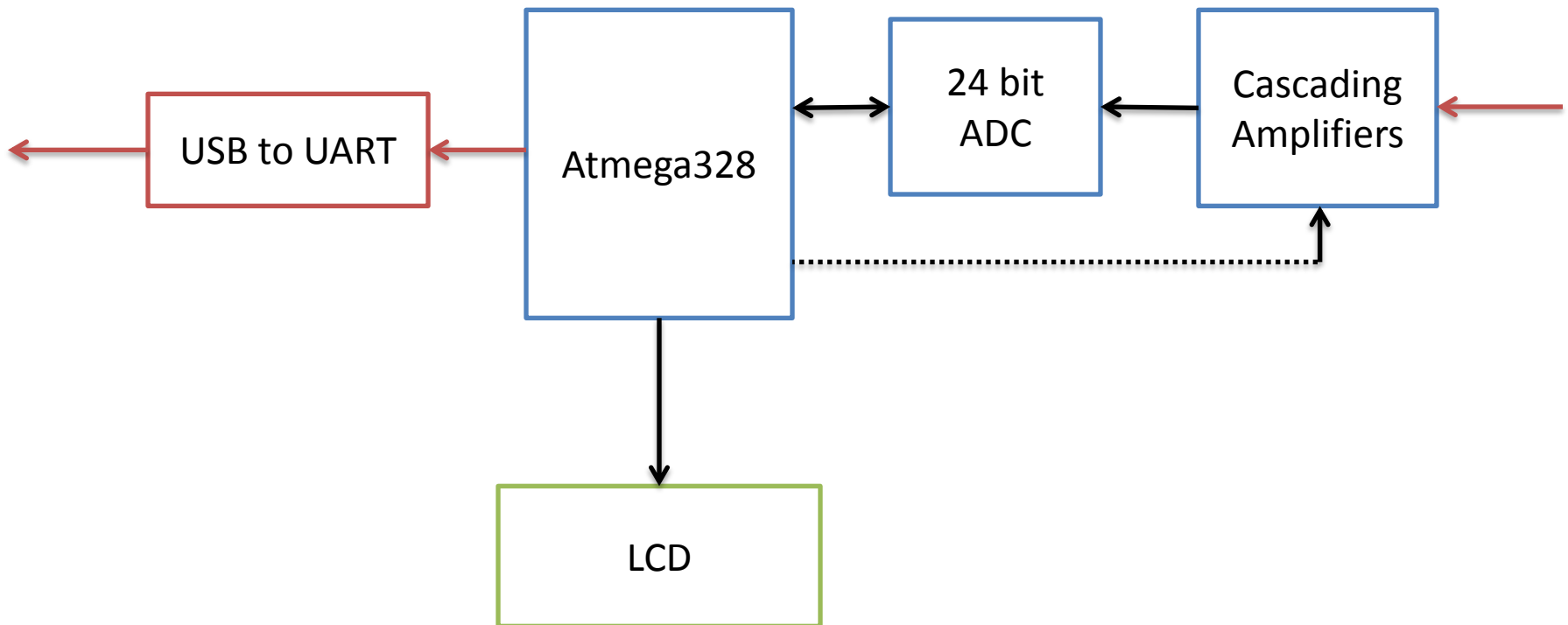
Hardware diagram



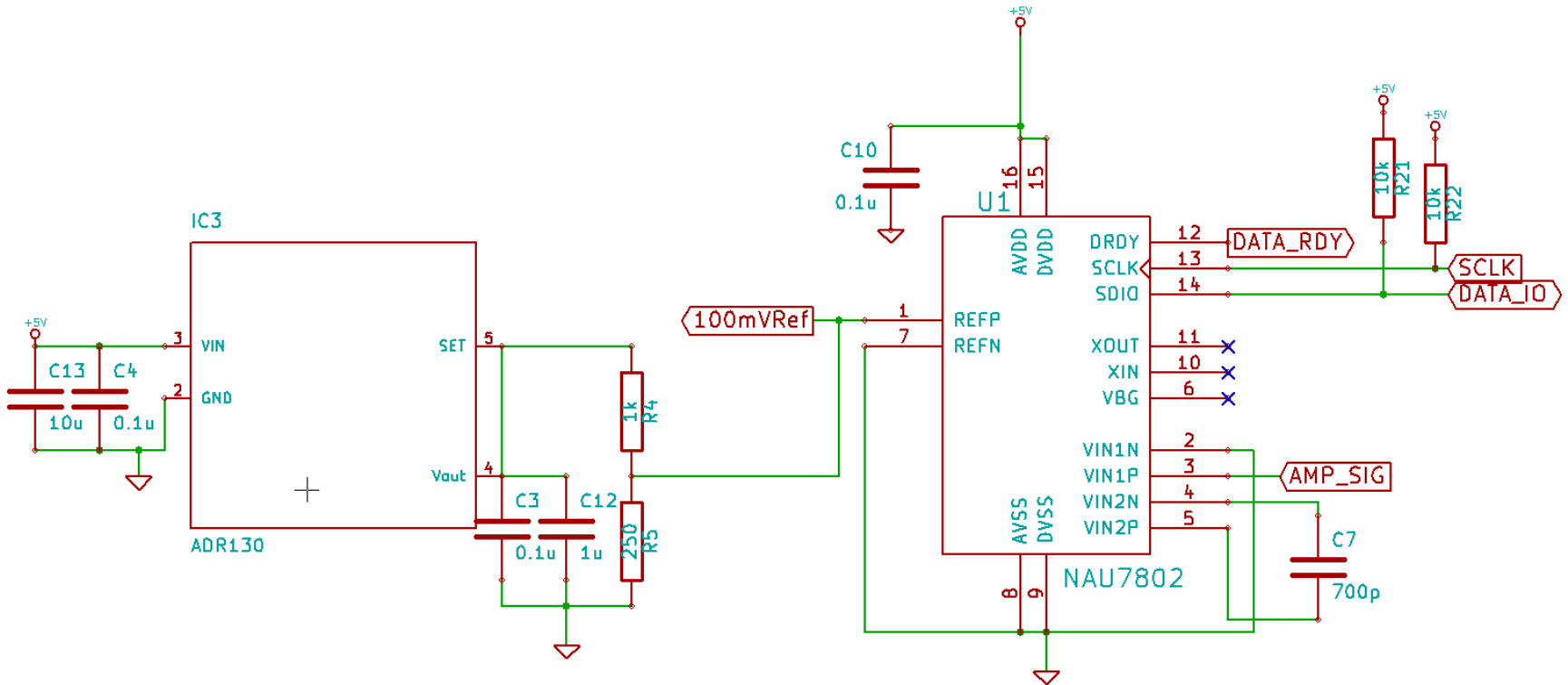
Atmega + Display



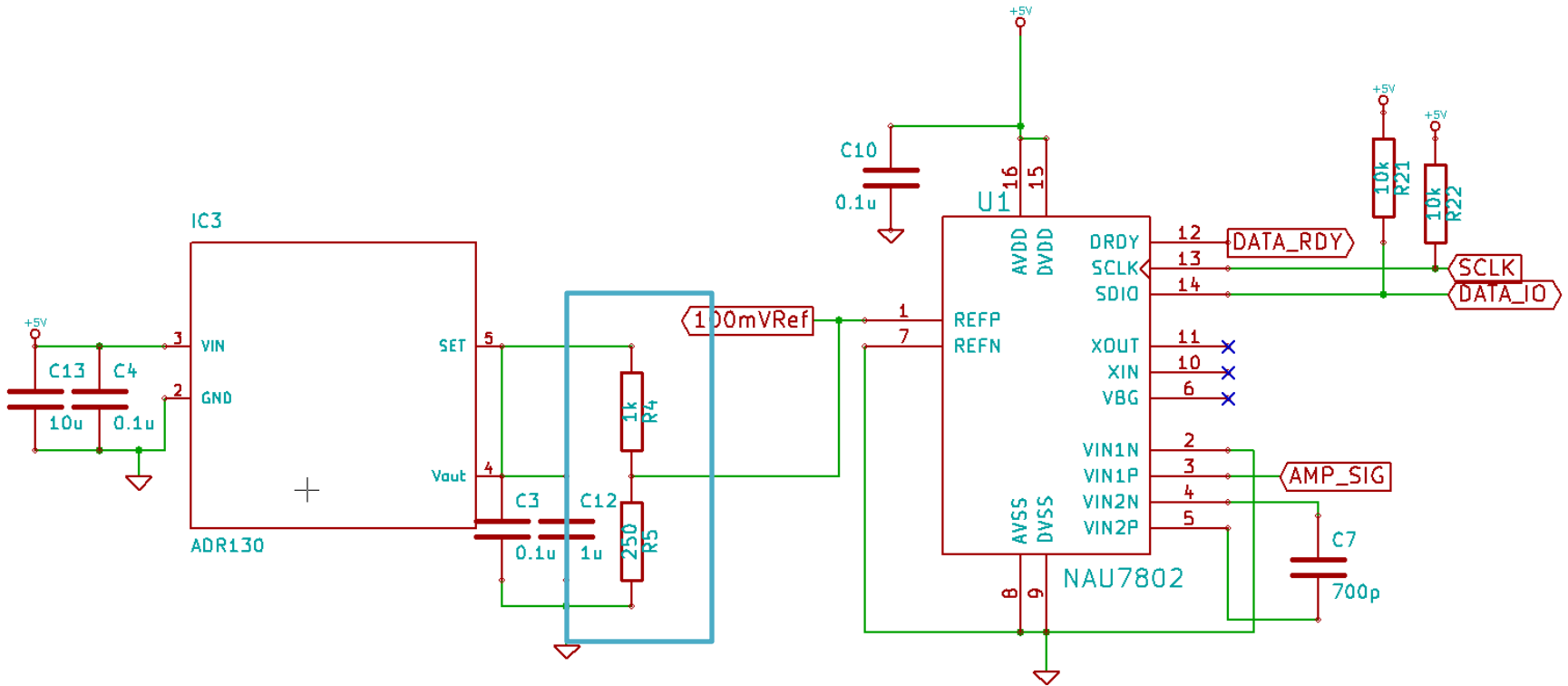
Hardware diagram



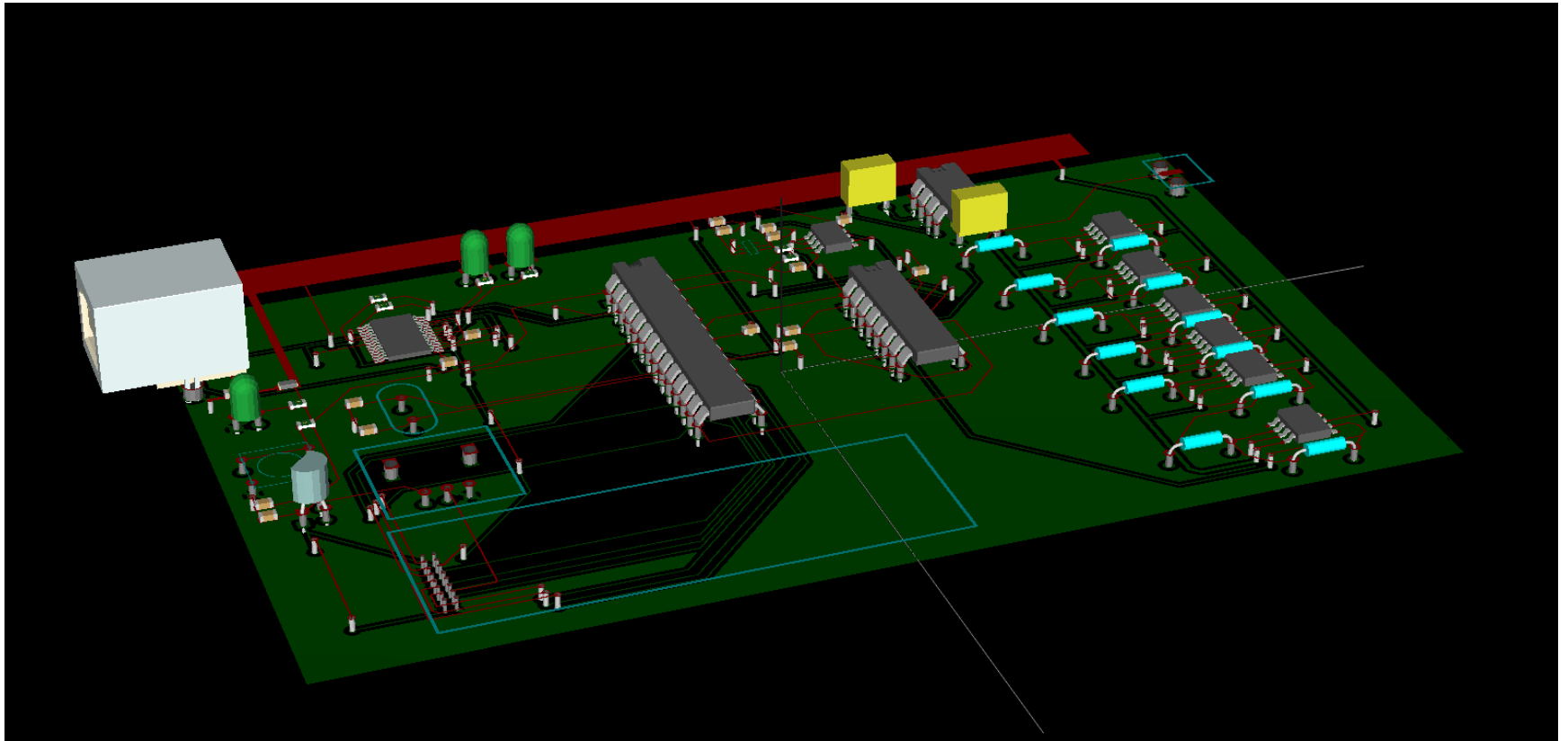
24-bit ADC



24-bit ADC



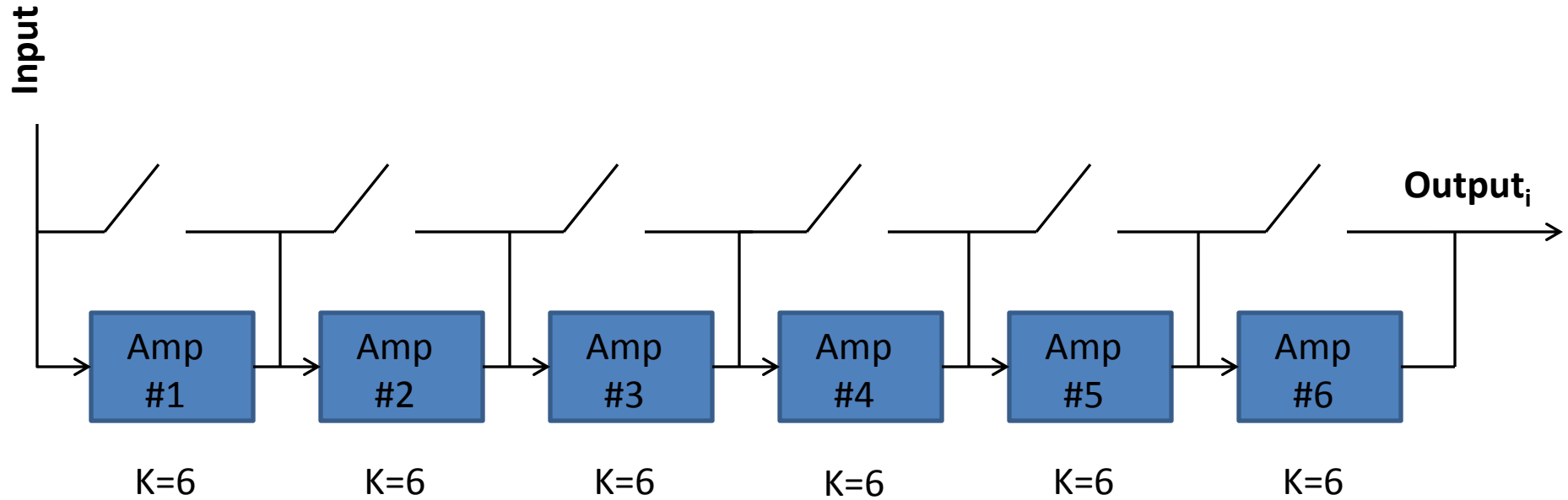
Original PCB layout



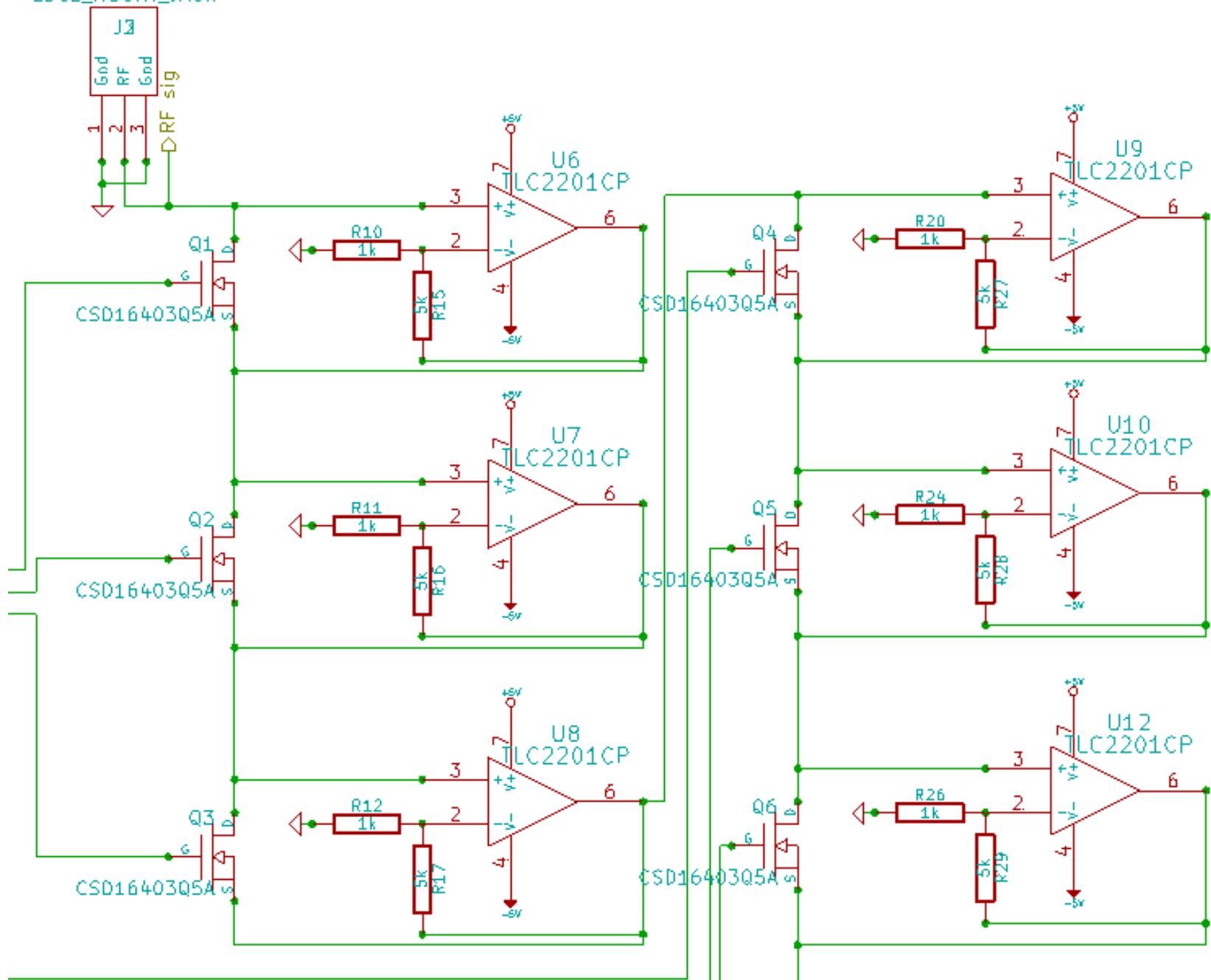
Amplifier Goals

- Signal has the ability to bypass the amplifier.
- The gain can be adjustable.
- Low noise
- Noise filtration

Amplifier Block Diagram



EDGE_MOUNT_JACK



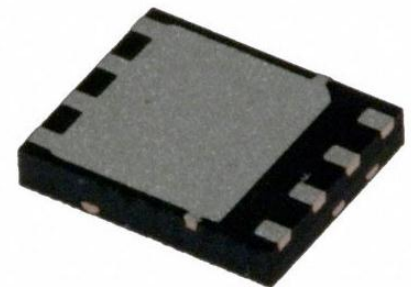
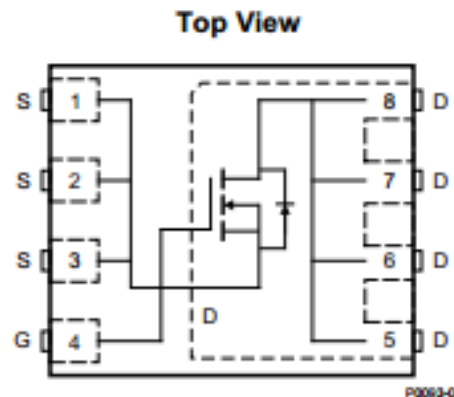
Op Amps Comparison

Model	Gain Bandwidth	Noise	Slew rate
OPA355	200 MHz	5.80 nV/√Hz	360 V/μs
OPA847	3.90 GHz	0.85 nV/√Hz	950 V/μs
TLC2201	1.90 MHz	12.0 nV/√Hz	2.70 V/μs



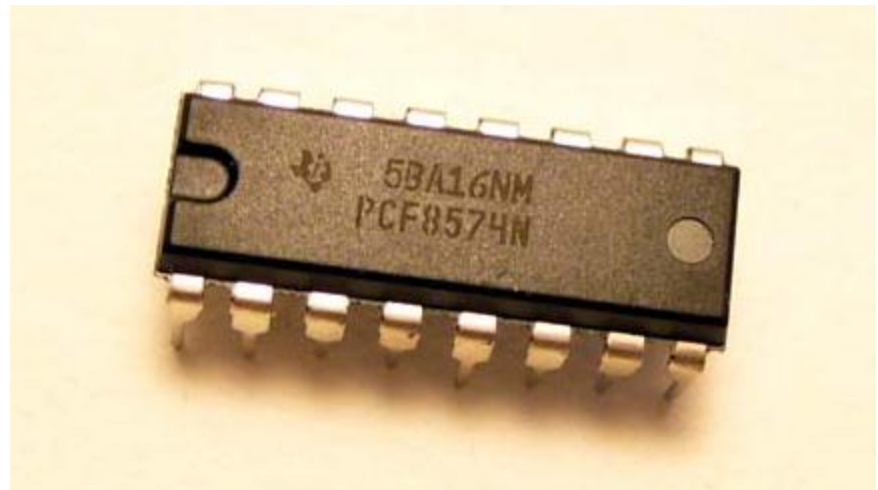
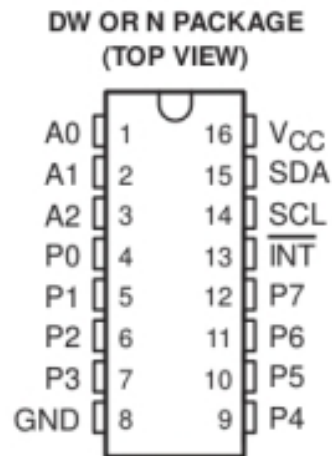
CSD16403Q5A

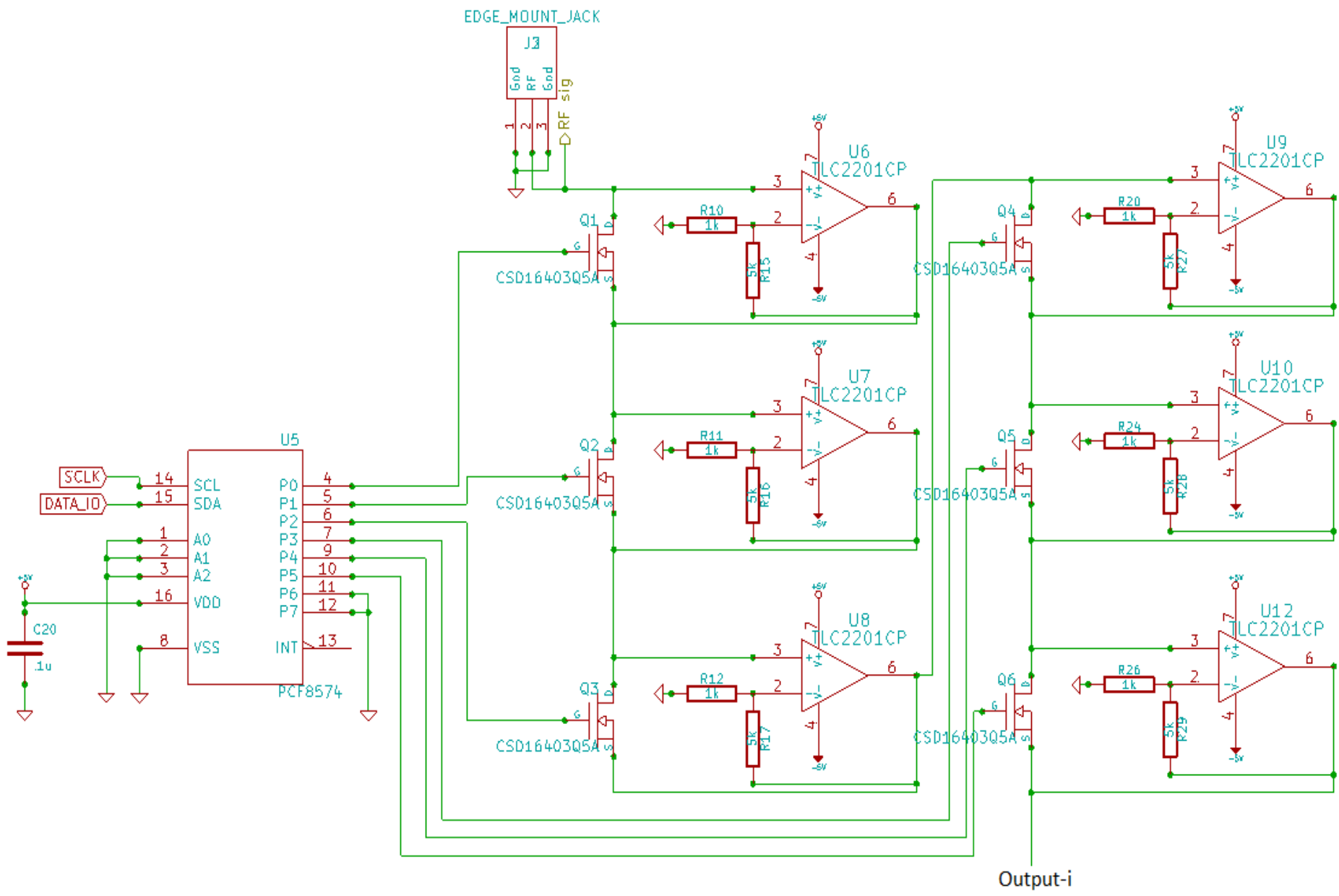
- N channel MOSFET
- Drain to Source Voltage (V_{dss}): 25V
- $V_{gs(th)}$ (Max) @ I_d : 1.9V @ 250 μ A
- $R_{ds\ On}$ (Max) @ I_d , V_{gs} : 2.8 mOhm @ 20A, 10V
- Surface mount



PCF8574

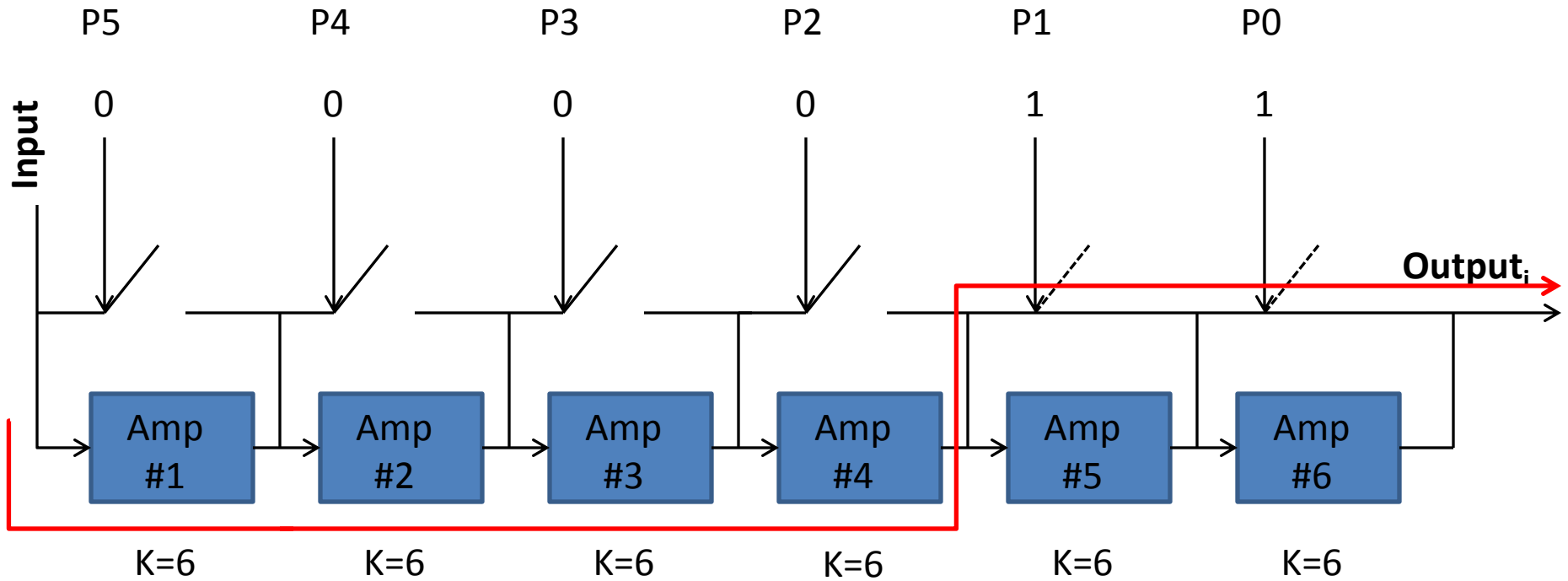
- 8 bits I/O port expander that uses the I2C protocol
- 2 ports of microcontroller to control up to 8 digital I/O ports. (SDA & SCL)



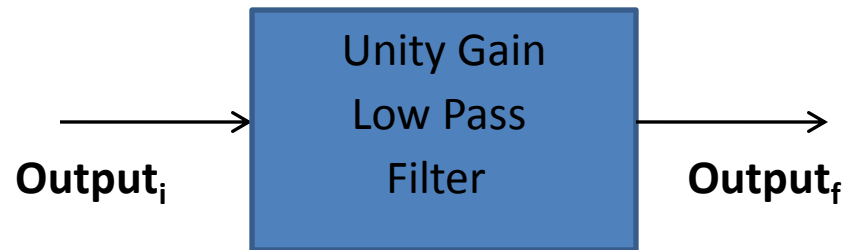


Output-i

Example



Amplifier Block Diagram

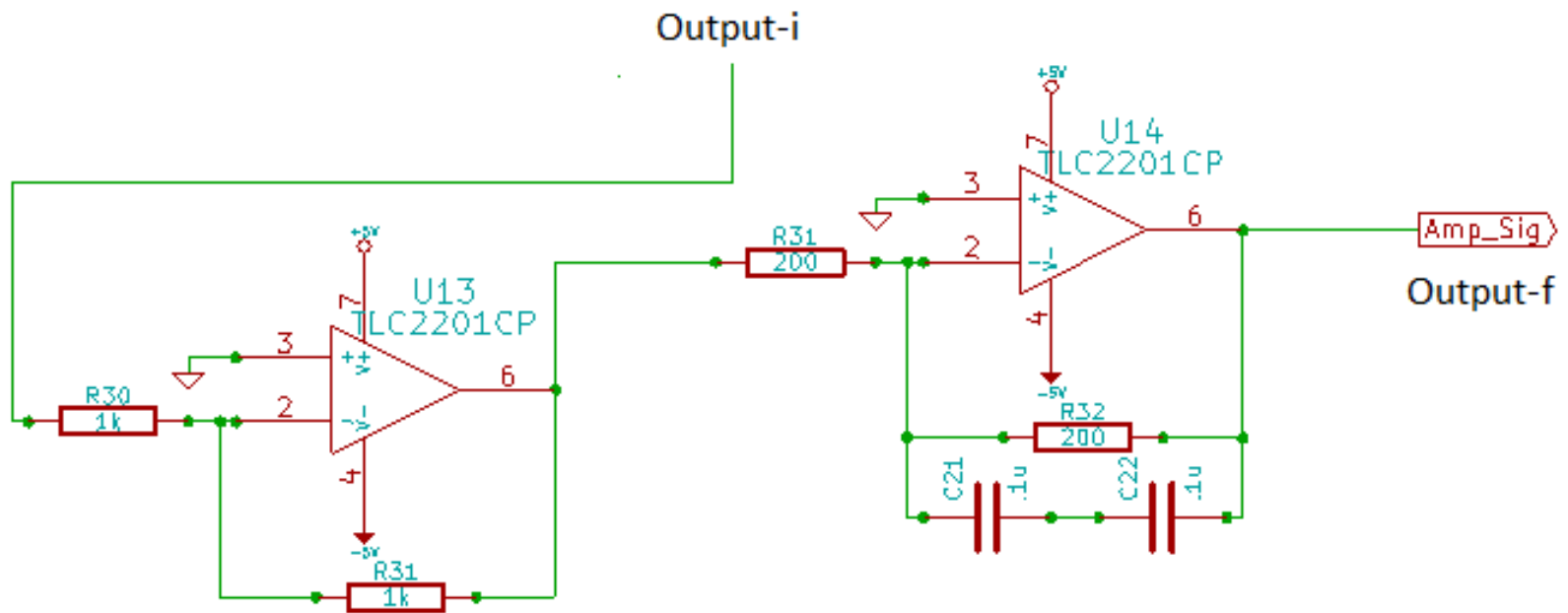


$$f_c = \frac{1}{2 \cdot \pi \cdot R \cdot C}$$

$$f_c = \frac{1}{2 \cdot \pi \cdot 200 \Omega \cdot [(.1 \mu F \cdot .1 \mu F) / (.1 \mu F + .1 \mu F)]}$$

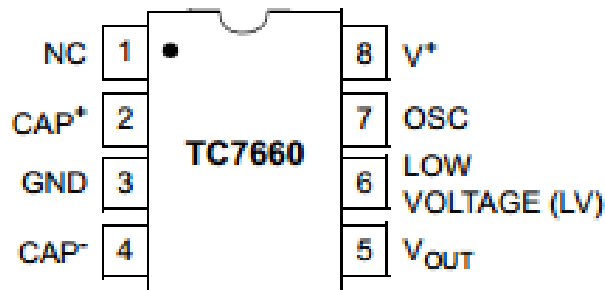
$$f_c \approx 15.915 \text{ kHz}$$

Low Pass Filter Sch.

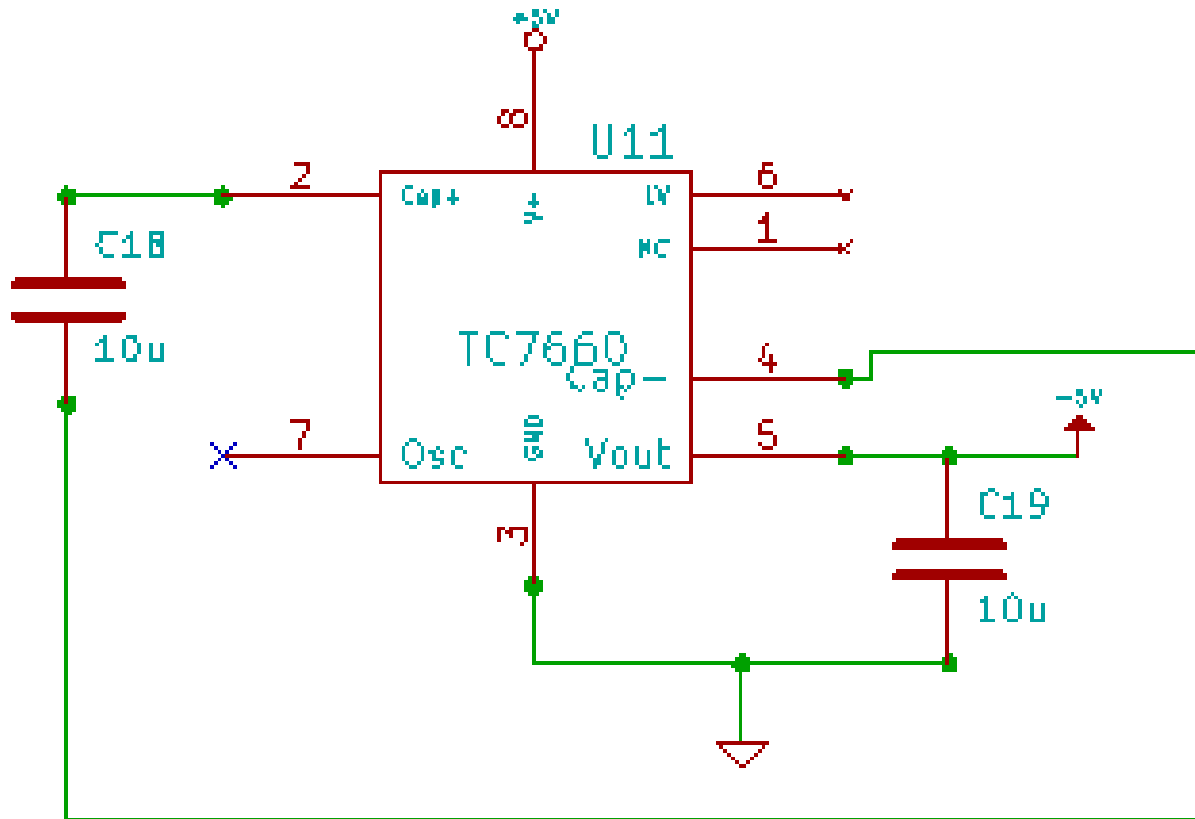


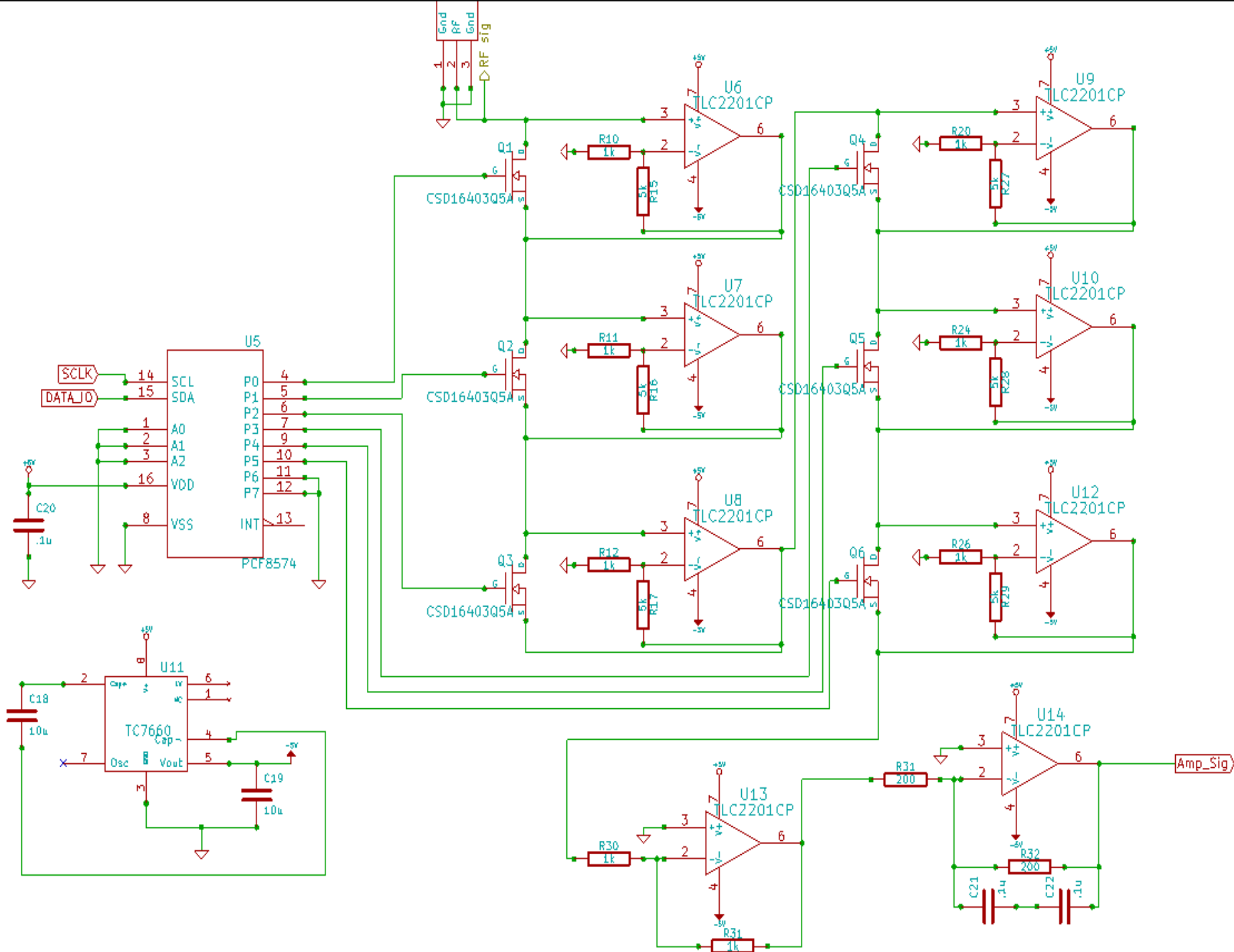
TC7660

- Converts +5V Supply to $\pm 5V$ System
- Efficient Voltage Conversion: 99.9%
- Excellent Power Efficiency: 98%
- Low Cost and Easy to Use



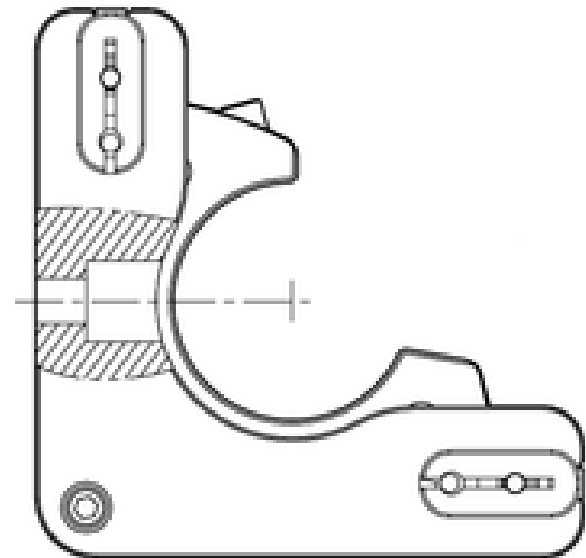
TC7660 Con. Schematic





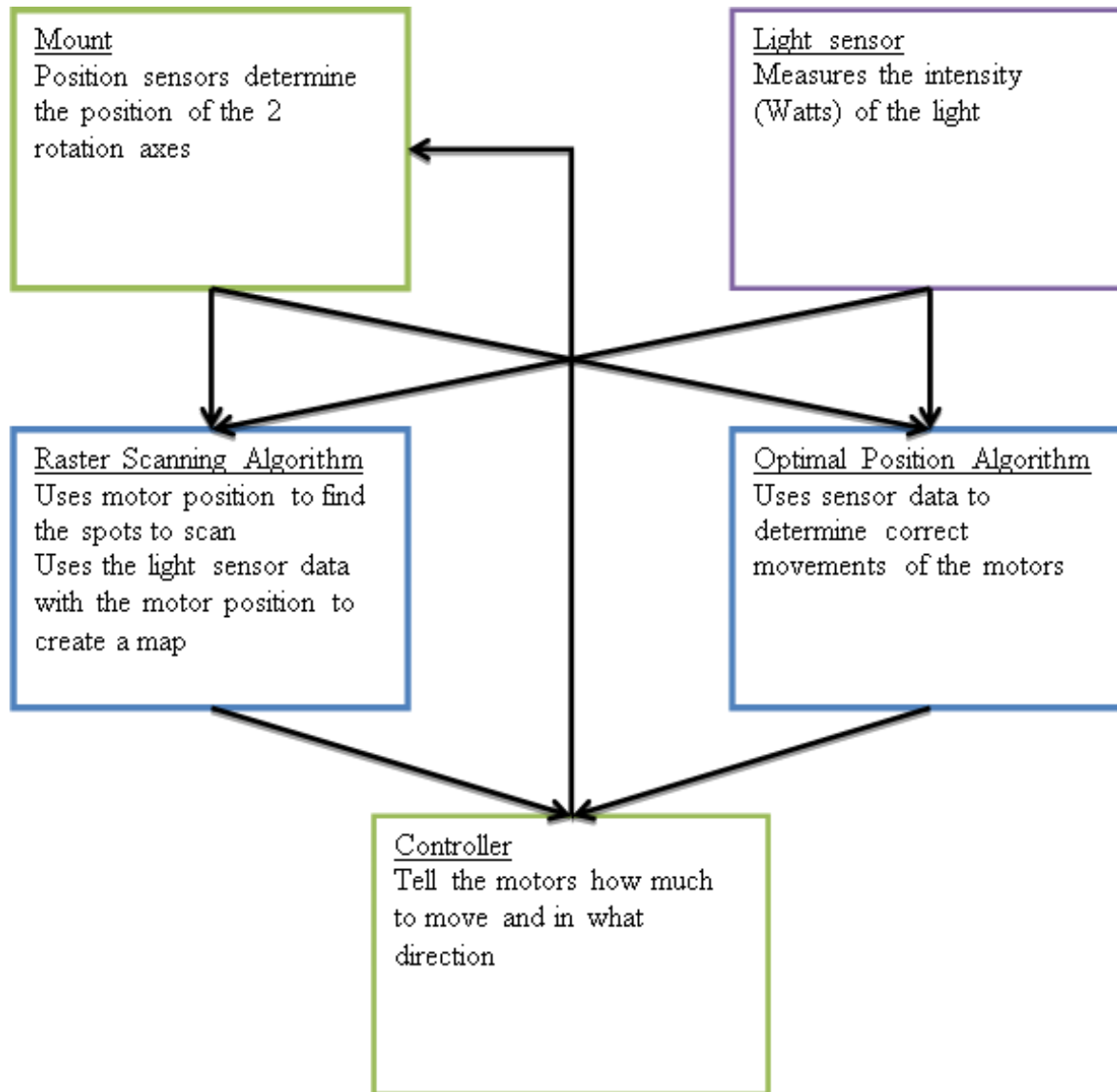
Piezo Motor

Newport AG-M100L	
Optical Diameter	1in (25.4mm)
Angular Range	$\pm 2^\circ$
Adjustment Sensitivity	1 μ rad
Absolute Positioning Accuracy	0.05 $^\circ$
Max. Speed	0.75 $^\circ$ /s
Thermal Tilt	4 μ rad/ $^\circ$ C



Back view of AG-M100L

Software/Hardware Interaction

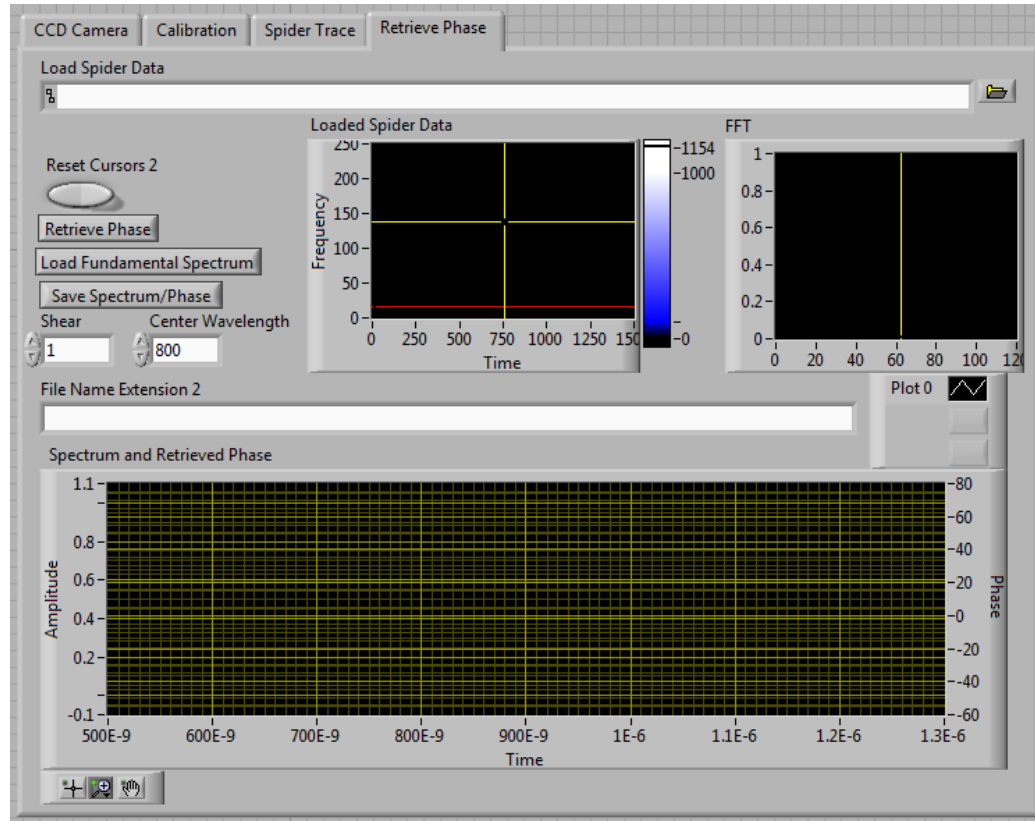


Software Benefits

- Automatically and manually rotate the crystal
- Increase position accuracy
- Decrease setup time
- Remove the inaccuracy of human movement



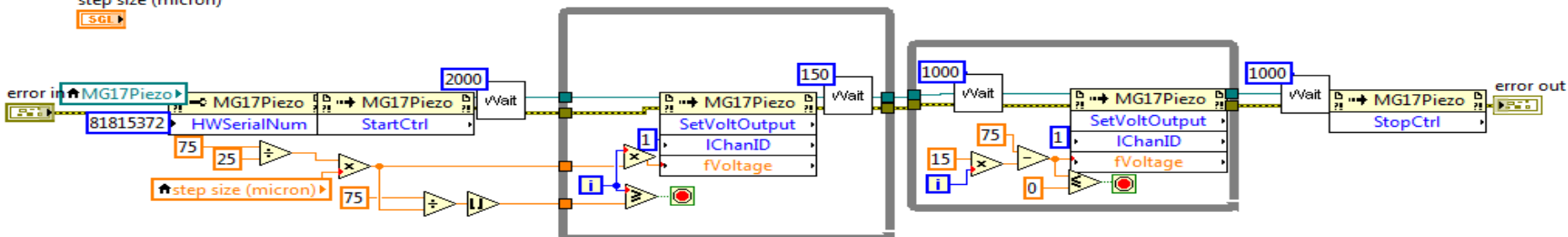
Software Environment



MG17Piezo



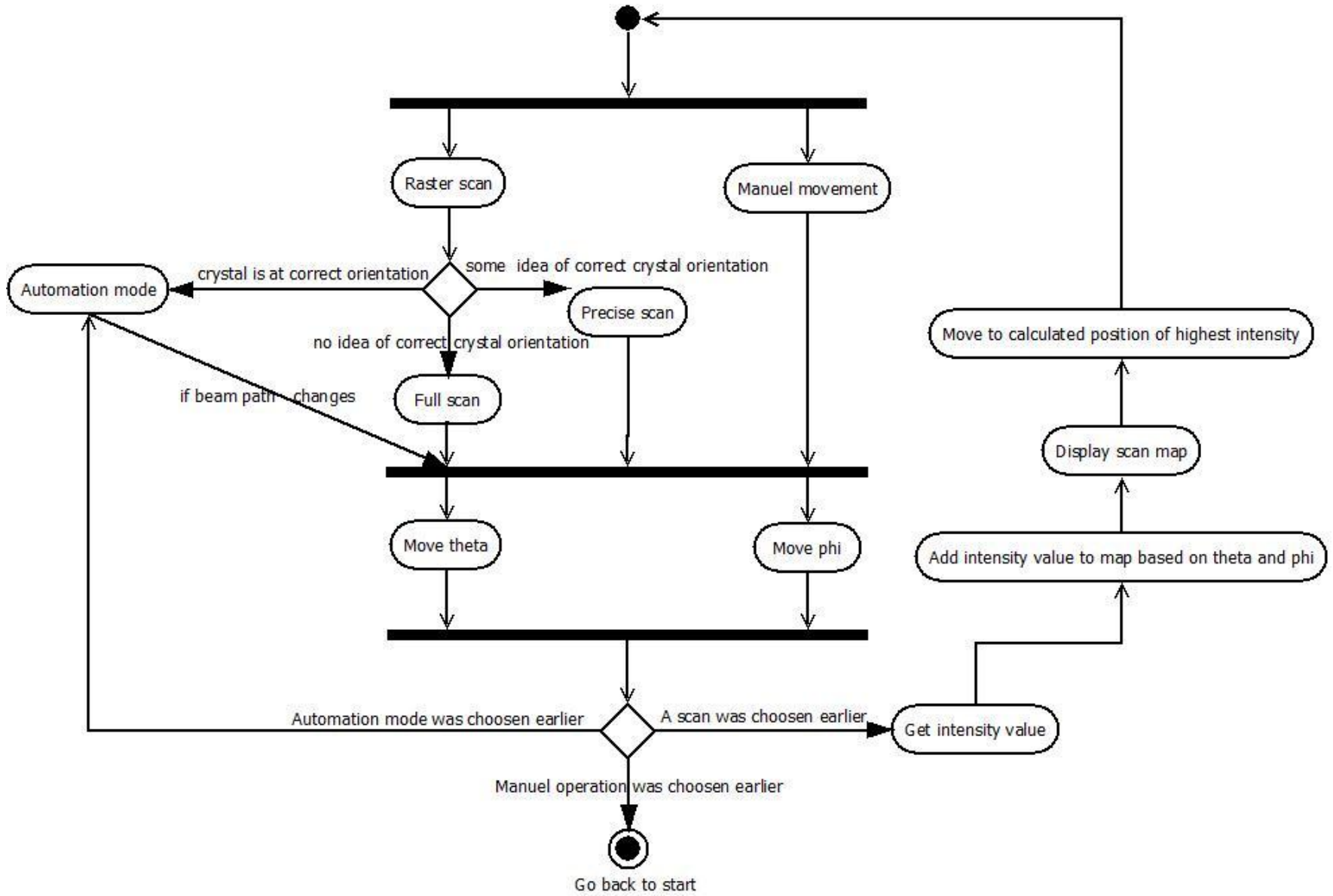
step size (micron)



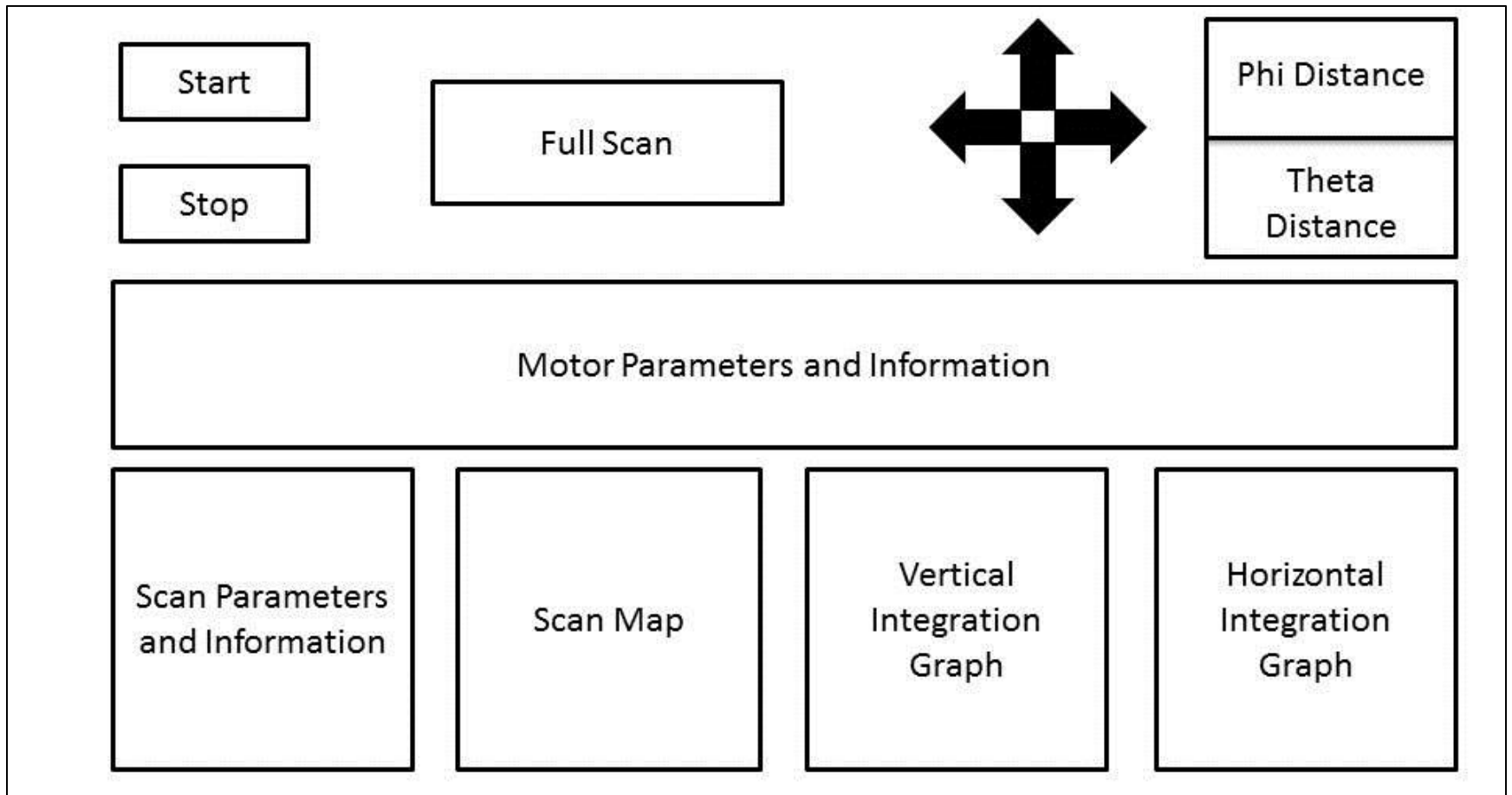
LabVIEW Benefits

- Graphical programming language
 - More difficult to make errors
 - Can quickly see how a program works
- Accepts MATLAB code and a “C like” script
- Parallel execution for multiple threads
- Execution highlighting (debug feature)
- Broken arrow start button lets you know there are errors

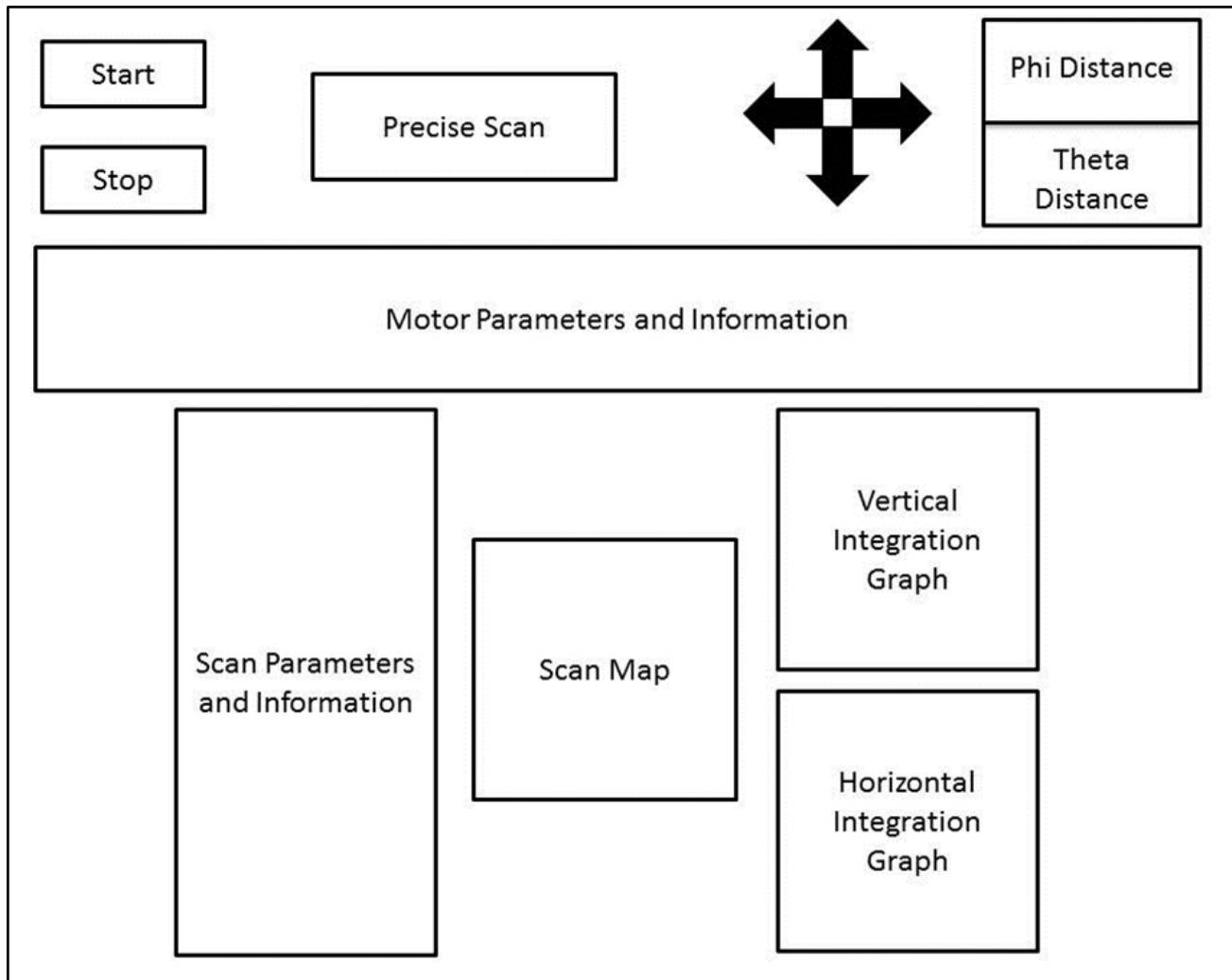
Activity Diagram



GUI



GUI



Current GUI

The GUI is organized into several functional areas:

- Instrument Key IN:** Includes an **OFF** button, a **STOP** button, and a **Full Scan** button.
- Theta/Phi Controls:** A central crosshair with **Theta** and **Phi** labels. Surrounding it are sliders for **Theta Distance**, **Theta Speed**, **Phi Distance**, and **Phi Speed**, all currently set to 0.
- Position Limits:** Fields for **Current Position**, **Home Position**, **Positive Theta Limit**, **Negative Theta Limit**, **Positive Phi Limit**, and **Negative Phi Limit**. A **Define Home** button is located below the position fields.
- Step Size and Speed:** Sliders for **Theta Step Size**, **Theta Speed**, **Phi Step Size**, and **Phi Speed**, all set to 0.
- Intensity Gauge:** A semi-circular gauge with a scale from 0 to 100, showing a red needle pointing to approximately 10.
- Scan Map:** A 10x10 grid of numerical values, all currently set to 0.
- Vertical Integration Plot:** A graph with **Intensity** on the y-axis (0-100) and **Position (steps)** on the x-axis (0-100). The plot area is currently black.
- Horizontal Integration Plot:** A graph with **Position (steps)** on the y-axis (0-100) and **Intensity** on the x-axis (0-100). The plot area is currently black.

Current GUI

Instrument Key IN

OFF

STOP

Precise Scan

Theta

Theta Distance 0

Theta Speed 0

Phi

Phi Distance 0

Phi Speed 0

Scan Parameters

Theta Step Size 0

Theta Speed 2 0

Theta Steps 1

Phi Step Size 0

Phi Speed 2 0

Phi Steps 1

Current Position

Home Position

Define Home

Positive Theta Limit

Negative Theta Limit

Positive Phi Limit

Negative Phi Limit

Intensity

0 20 40 60 80 100

100

Scan Map

0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0

Verticle Integration

Plot 0

Intensity

Position (steps)

Horizontal Integration

Plot 0

Position (steps)

Intensity

The screenshot displays a software interface for instrument control. At the top left, there's an 'Instrument Key IN' section with 'OFF' and 'STOP' buttons, and a 'Precise Scan' button. A central 'Theta' section features a four-way arrow icon and sliders for 'Theta Distance' and 'Theta Speed', both set to 0. Below this is a 'Phi' section with sliders for 'Phi Distance' and 'Phi Speed', also set to 0. To the right, the 'Scan Parameters' section includes sliders for 'Theta Step Size', 'Theta Speed 2', '# Theta Steps', 'Phi Step Size', 'Phi Speed 2', and '# Phi Steps'. Below the parameters is a semi-circular 'Intensity' gauge with a scale from 0 to 100. The bottom left shows a 'Scan Map' as a 16x7 grid of zeros. The bottom right contains two empty plots: 'Verticle Integration' and 'Horizontal Integration', both labeled 'Plot 0'.

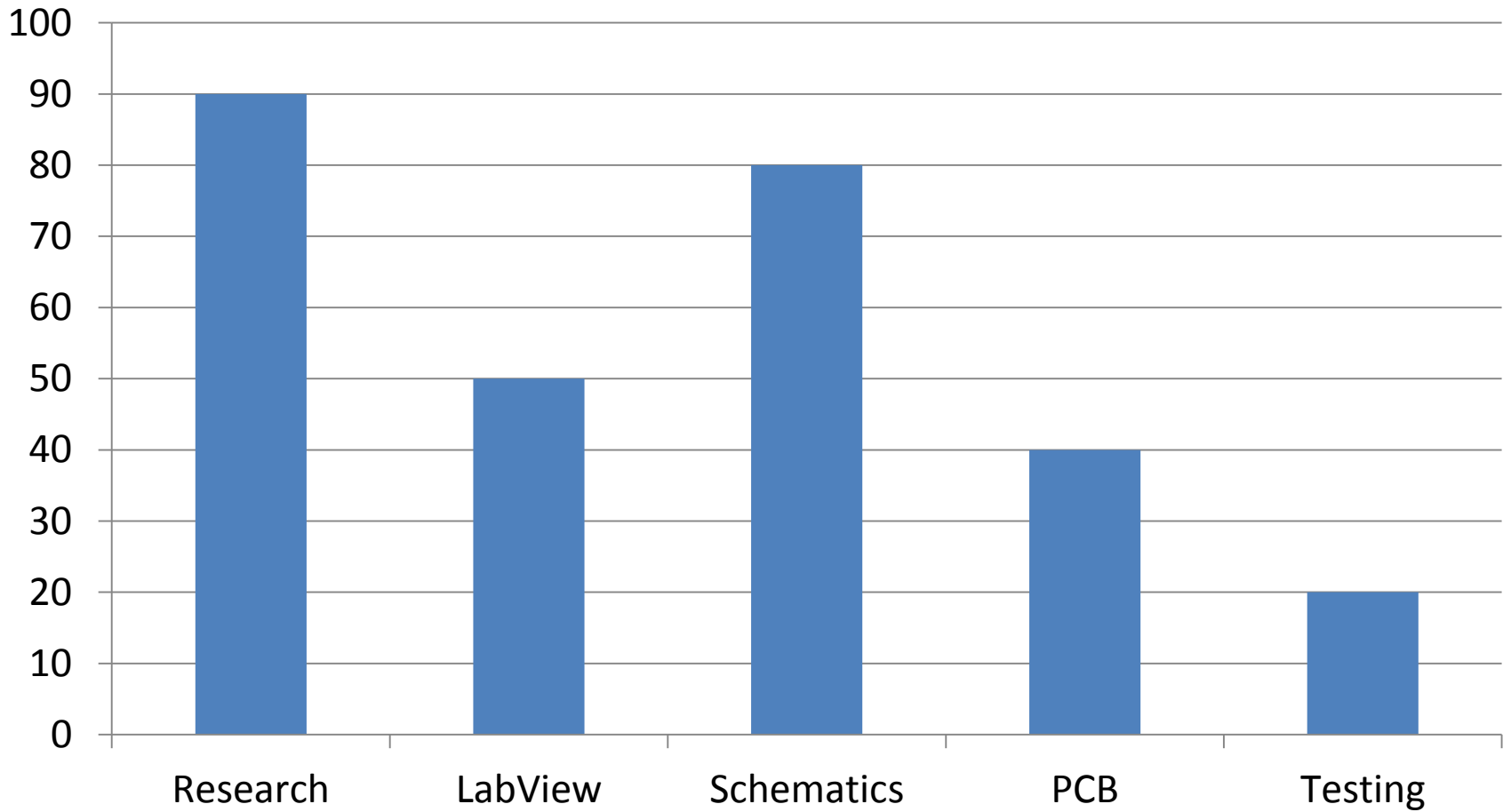
Component name	Subtotal	Our Cost
Resistors/Caps	29.93	0
24 bit ADC	2.47	0
3.3V regulator	0.54	0
Atmega328	3.93	0
ADR130	3.91	0
LEDs	1.11	0
Crystal 16Mhz	0.56	0
Ferrite bead	0.64	0
FT232R- USB to Serial IC	4.5	0
L78L33C	9.5	0
LCD Module	9.5	0
NAU7802	1.71	0
N-MOSFET	3.42	0
PCF8574	1.91	0
Precision 0.5v reference	3.07	0
Resistor 1k - 0.05% (Reference V divider)	4.36	0

Component name	Subtotal	Our Cost
Resistor 250 - 0.05% (Reference V divider)	5.33	0
Switch Button	0.1	0
SMA Female Edge Connector	4.86	0
TC7660	0.95	0
TLC2201CP Op Amp	16.5	0
USB A to B cable 3'	2.02	0
USB B Connector Female	0.54	0
X7R	0.11	0
Voltage inverter -5V	0.95	0
LCD Module	9.5	0
Mirror Mount	732	0
Motor Controller	419	0
PCB	66	0
Total	1338.92	0

Project Delegation

	Roberto	Chris	Hung
Full Scan Process	15%	80%	5%
Precise Scan Process	15%	80%	5%
Hardware/Software Integration	20%	60%	20%
Data Acquisition	70%	30%	0%
Microcontroller	90%	10%	0%
Display	100%	0%	0%
Amplifier	10%	0%	90%
PCB	40%	0%	60%

Progress



Current Problems

- Getting the maximum number of useful bits from conversion
- Reducing noise on the PCB traces
- Noise introduced during the amplification process
- Create a grayscale of the scan map with optimal position highlighted

Questions?