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Panel Session “Dynamic Modeling in Distribution”

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Reduced-Order DER Dynamic Models from Machine Learning

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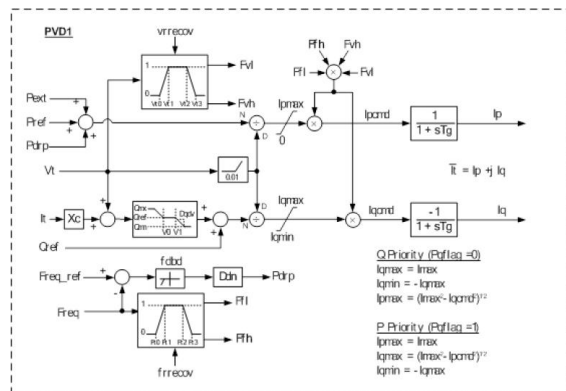
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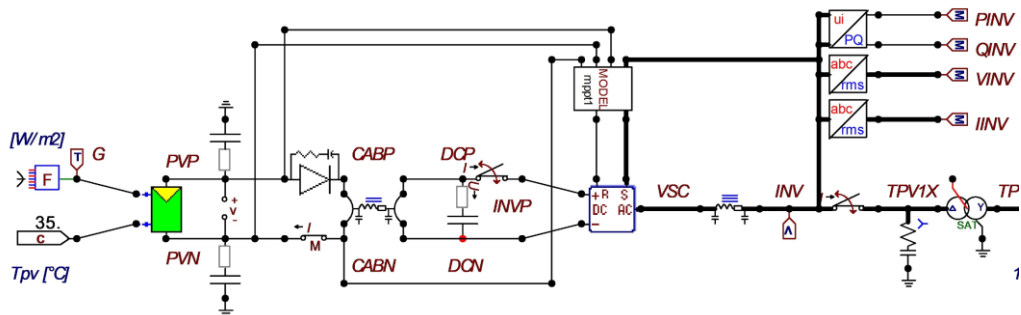


DER Dynamic Modeling

- Two main types: 1) Phasor domain (PVD1, DER_A) and 2) EMT detailed modeling
- Control is part of the model (implicitly or explicitly)



PVD1



An EMT model of a PV system in ATP

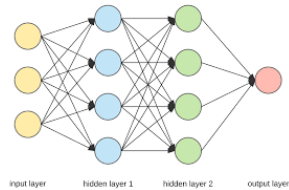
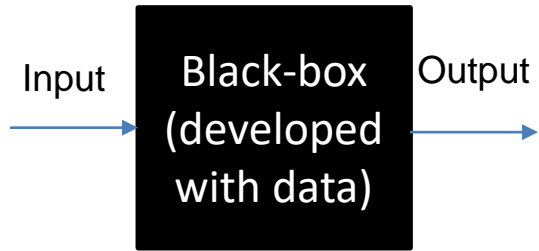
Lack of DER models suitable for both control design and transient simulation

- Phasor models have to neglect some details and internal variables that are important for control design
- EMT type models tend to be computationally intensive and difficult to scale for system-level control design
- Need to develop separate models:
 - e.g., MATLAB/Simulink models for control design, ATP, PSCAD or EMTP models for transient simulation

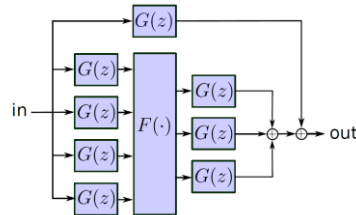
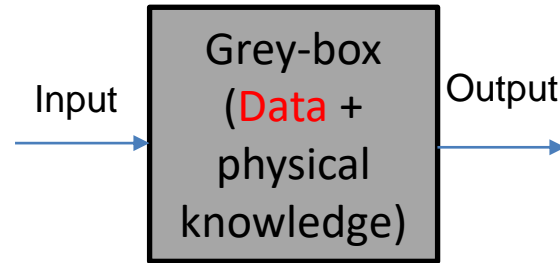
Our objective is to develop DER dynamic models that are suitable for both control design and transient simulation.

Data-driven reduced-order modeling of DER

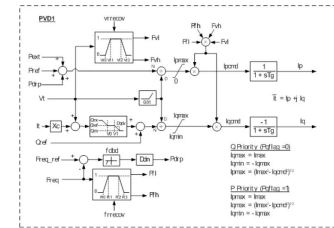
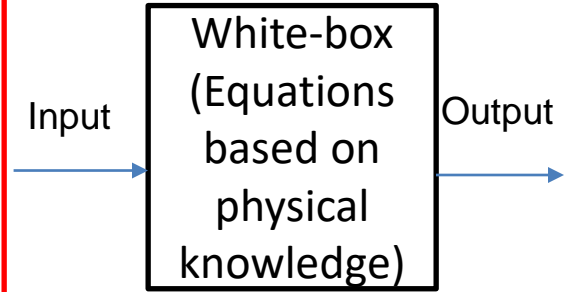
- Black-box, grey-box and white-box modeling



Neural network



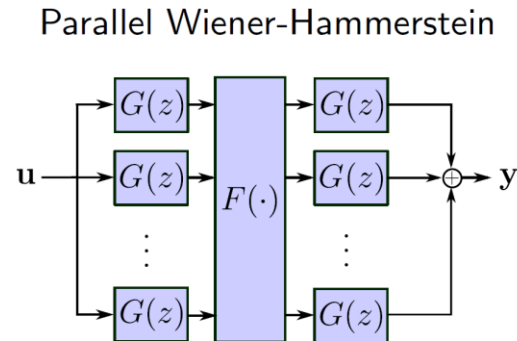
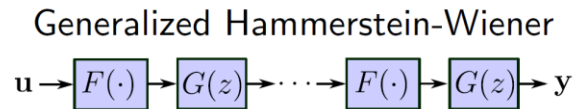
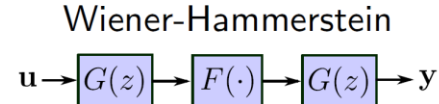
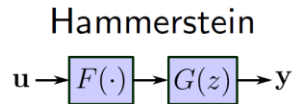
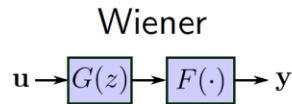
Block-oriented dynamic model
(e.g., Hammerstein-Wiener model)



Physics-based model

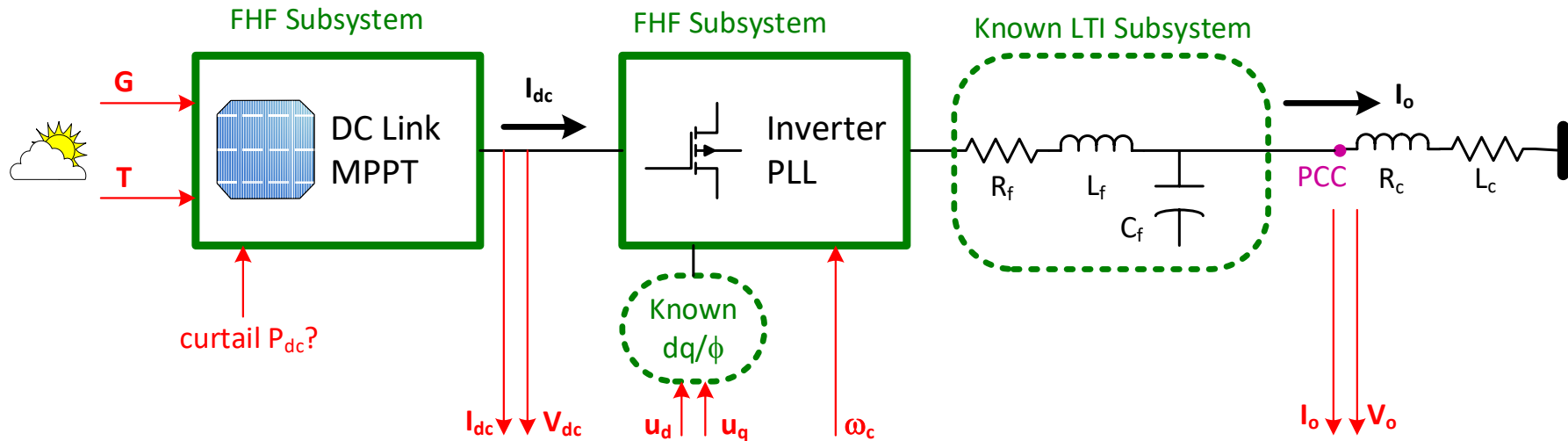
Hammerstein-Wiener (HW) models

Block-oriented architectures consist in the interconnection of transfer functions $G(z)$ and static non-linearities $F(\bullet)$

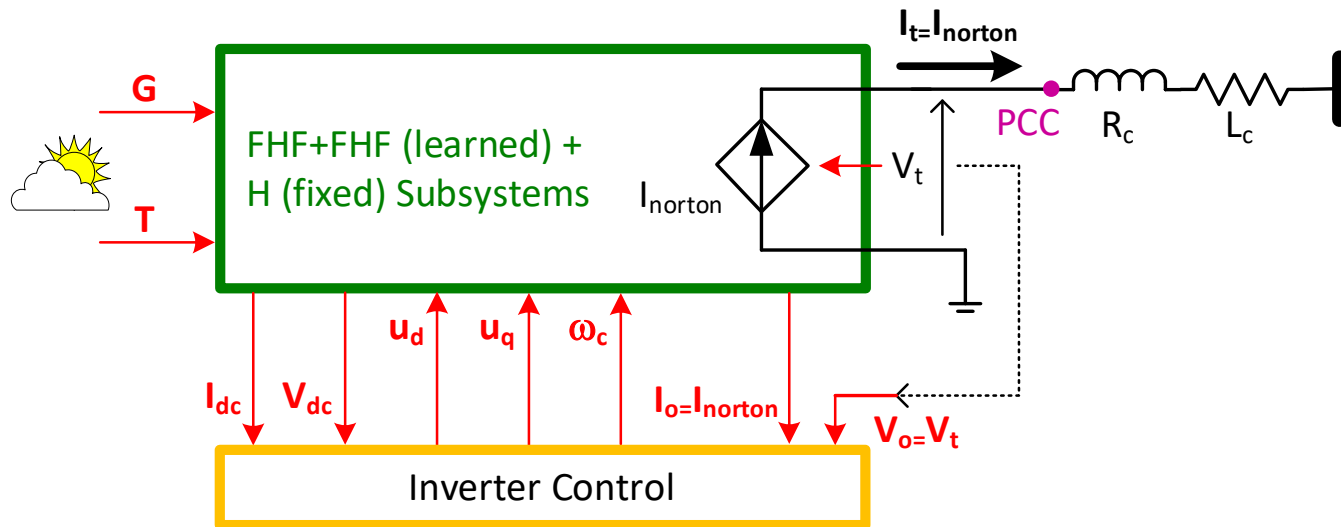


Our framework for training a PV solar model

Interface variables from **control viewpoint** shown in red. For training, V_o is an input.



Controlled current source interfaces HW model to the grid



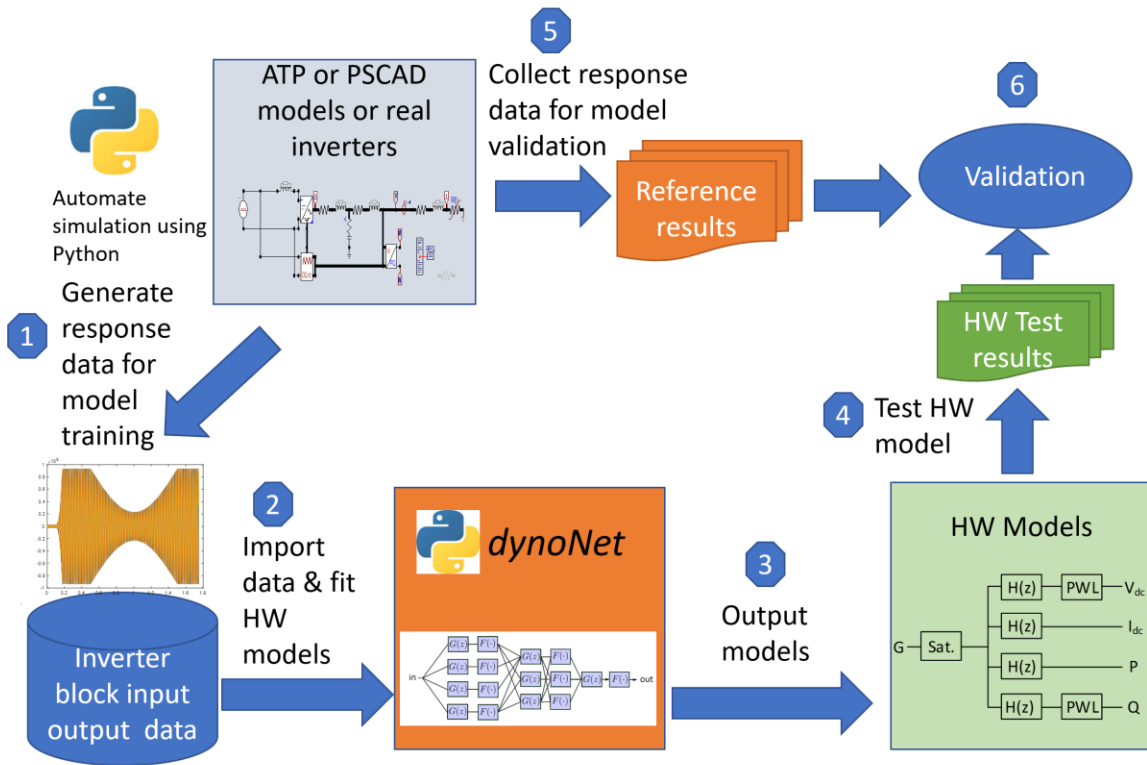
Code: <https://github.com/pnnl/pecblocks>

(Open-source license based on Berkeley Software Distribution [BSD-3])

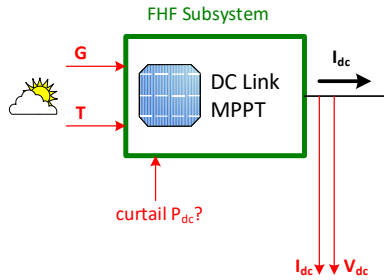
dynoNet: A neural network architecture for learning dynamical systems

- An open-source python tool tailored for sequence modeling and dynamical system identification using a **neural network architecture**.
- HW models can be trained end-to-end by plain **back-propagation**.
- Support rich class of non-linear, causal dynamic relations (e.g., multi-input and multi-output with arbitrary block interconnections).
- Codes:
 - Original: <https://github.com/forgi86/dynonet>
 - Our work: <https://github.com/pnnl/pecblocks>

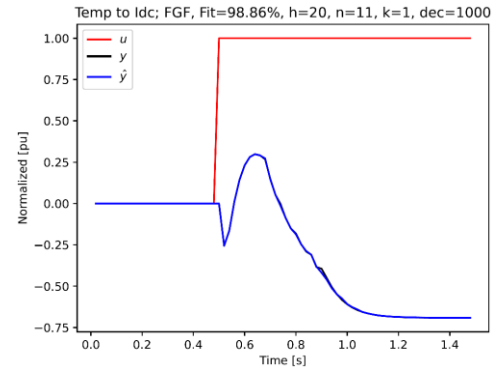
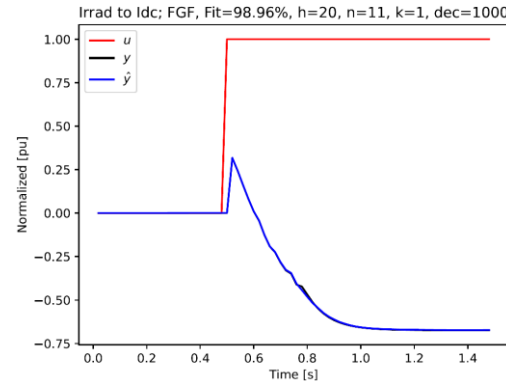
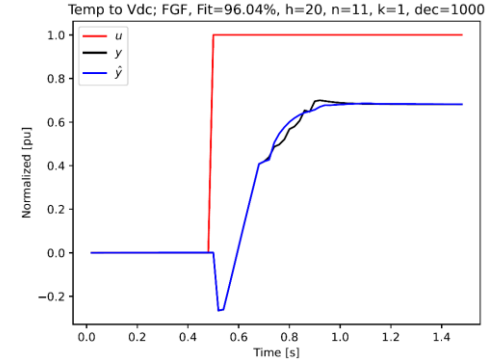
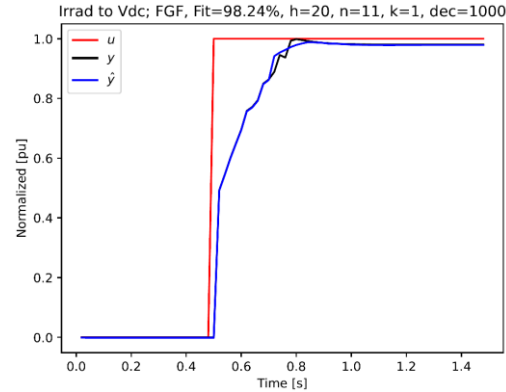
Workflow



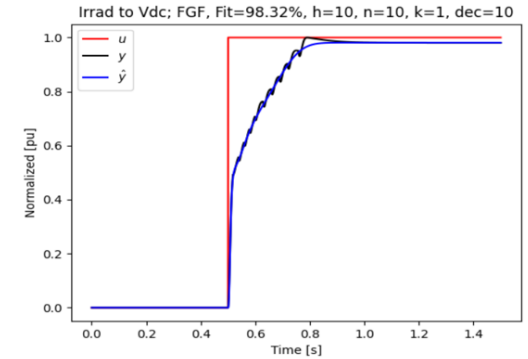
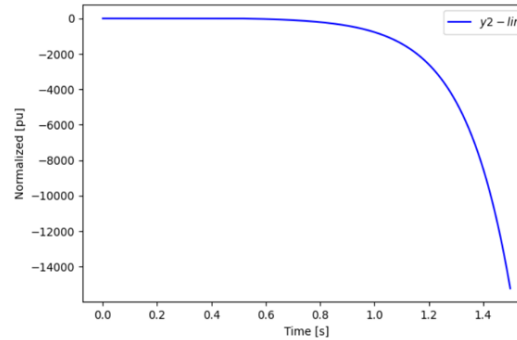
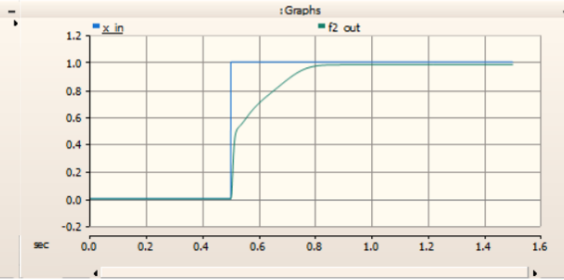
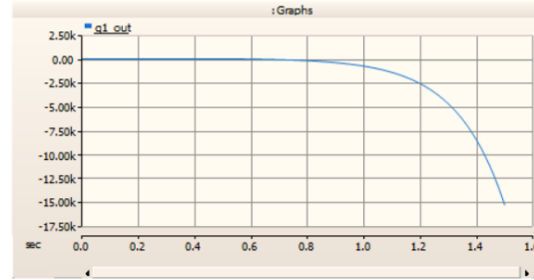
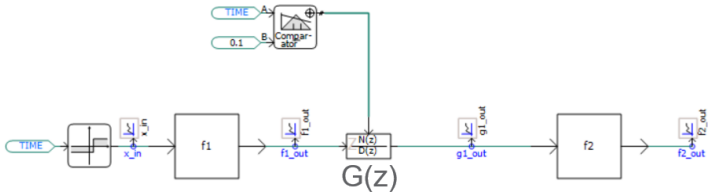
Test Results: $G, T \rightarrow V_{dc}, I_{dc}$



- Input u is normalized to its magnitude of change
- Outputs y also normalized to magnitude of change, i.e., $(\max - \min) = 1$
- FGF denotes HW block cascade, 20 hidden nodes, 11th-order G, $Dt=20\text{ms}$ for DC, 1-step delay on G



Comparison of PSCAD to dynoNet result



Summary

- Grey-box, block-oriented dynamic modeling of DERs can meet the needs of both control design and efficient transient simulation.
- We have developed a deep-learning based approach for deriving cascaded Hammerstein-Wiener models for a solar PV system and showed promising results.
- Our work is open-sourced on GitHub:
<https://github.com/pnnl/pecblocks>

Acknowledgement

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Thank You!

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